



DEPARTMENT OF ELECTRICAL ENGINEERING

*Scheme of Instruction
and
Syllabi of*

M.E. (ELECTRICAL ENGINEERING)

Specialization of
Industrial Drives and Control
(Full Time & CEEP)

2024 - 2025



UNIVERSITY COLLEGE OF ENGINEERING

(AUTONOMOUS)

OSMANIA UNIVERSITY
HYDERABAD – 500 007, TELANGANA

UNIVERSITY COLLEGE OF ENGINEERING

Vision

The Vision of the Institute is to generate and disseminate knowledge through a harmonious blending of Science, Engineering and Technology. To serve the society by developing a modern technology in students' heightened intellectual, cultural, ethical and humane sensitivities, fostering a scientific temper and promoting professional and technological expertise.

Mission

- To achieve excellence in Teaching and Research
- To generate, disseminate and preserve knowledge
- To enable empowerment through knowledge and information
- Advancement of knowledge in Engineering, Science and Technology
- Promote learning in free thinking and innovative environment
- Cultivate skills, attitudes to promote knowledge creation
- Rendering socially relevant technical services for the community
- To impart new skills of technology development
- To inculcate entrepreneurial talents and technology appreciation programs
- Technology transfer and incubation

DEPARTMENT OF ELECTRICAL ENGINEERING

Vision

To strive for excellence in education and research; meet the requirement of industry in the field of electrical engineering to serve the nation.

Mission

- To provide knowledge-based technology and service to meet the needs of society in electrical and allied industries.
- To help in building national capabilities for excellent energy management and to explore non-conventional energy sources.
- To create research-oriented culture and to provide competent consultancy.
- To create and sustain environment of learning in which students acquire knowledge and learn to apply it professionally with due consideration of ethical and economic issues.
- To be accountable through self-evaluation and continuous improvement.

M.E. ELECTRICAL ENGINEERING

(Industrial Drives and Control)

Programme Educational Objectives

- PEO1 To prepare the students for acquiring the knowledge of different types of Industrial drives including special electric drives controlled with various power electronic converters.
- PEO2 To develop the ability to exhibit creative and critical reasoning skills to comprehend, analyze, design and implement solutions for problems in power electronic converters and drives.
- PEO3 To prepare the students for successful carrier in Industry, Academia and Research with proficiency in control of electric drives.

Programme Outcomes

- PO1 An ability to independently carry out research/ investigation and development to solve practical problems.
- PO2 An ability to write and present a substantial technical report/document.
- PO3 Students should be able to demonstrate a degree of mastery over the area of industrial drives and control specialization of the problem. The mastery should be at level higher than the requirements in the appropriate bachelor program.
- PO4 The student will be able to apply critical and innovative skills to model design and develop simulation software solutions to solve the problems of power electronic converters and drives.
- PO5 Students will be able to analyze and design different types of renewable energy generation topologies for various electrical applications.
- PO6 Students will be able to acquire knowledge in state-of-the-art technologies, with effective communication.

SCHEME OF INSTRUCTION AND EVALUATION

M.E. - Industrial Drives and Control

S. No.	Type of course	Course Code	Course Name	Contact hours per week		Scheme of Examination		Credits
				L	P	CIE	SEE	
SEMESTER-I								
1	Core-I	EE 3101	Static Control of D.C. Drives	3	-	40	60	3
2	Core-II	EE 3102	Machine Modeling and Analysis	3	-	40	60	3
3	Core-III	EE 3103	Control of Electric Drives	3	-	40	60	3
4	Programme Elective - I	EE 3111	Special Electrical Machines	3	-	40	60	3
		EE 3112	Neural Networks and Fuzzy Logic					
		EE 3113	Renewable Energy Sources					
		EE 3114	Power Electronics Applications to Power Systems					
5	Programme Elective - II	EE 3121	Reliability Engineering	3	-	40	60	3
		EE 3122	Advanced Optimization Techniques					
		EE 3123	Digital Control of Power Electronics					
		EE 3302	Power Electronic Converters for Renewable Energy					
6	Programme Elective - III	EE 3131	Industrial Controllers	3	-	40	60	3
		EE 3132	Advanced Microprocessors					
		EE 3133	Programmable Logic Controllers					
		EE 3134	Digital Signal Processing					

		EE 3135	Python Programming					
7	Laboratory - I	EE 3151	Drives Laboratory - I	-	2	50	-	1
8	Seminar - I	EE 3161	Seminar - I	-	2	50	-	1
	TOTAL			18	4	340	360	20
SEMESTER-II								
1	Core-IV	EE 3104	Dynamics of Electric Machines	3	-	40	60	3
2	Core-V	EE 3105	Static Control of A.C. Drives	3	-	40	60	3
3	Core-VI	EE 3106	Power Electronic Converters	3	-	40	60	3
4	Programme Elective-IV	EE 3141	Modern Control Theory	3	-	40	60	3
		EE 3142	Smart Grid Technologies					
		EE 3143	Grid Integration of Distributed Generation					
5	Programme Elective-V	EE 3124	Hybrid Electric Vehicles	3	-	40	60	3
		EE 3152	Digital Circuits and Logic Design					
		EE 3351	Battery management systems and charging stations					
6	Open Elective	OE 901 EE	Waste to Energy	3	-	40	60	3
		OE 902 EE	Power Plant Control and Instrumentation					
		OE 941 CS	Business Analytics					
		OE 942 ME	Industrial Safety					
		OE 943 ME	Operations Research					
		OE 944 CE	Cost Management of Engineering Projects					
		OE 945 ME	Composite Materials					
		OE 941 BM	Medical Assistive Devices					
		OE 942 BM	Medical Imaging Techniques					
OE 941 LA	Intellectual Property Rights							
7	Mini Project	EE 171	Mini Project	-	4	50	-	2

8	Laboratory - II	EE 152	Drives Laboratory - II	-	2	50	-	1
9	Laboratory - III	EE 153	Drives Laboratory - III	-	2	50	-	1
TOTAL				18	8	390	360	22
SEMESTER-III								
1	Audit Course – I (Online)	AC030EE	Engineering Research Methodology in Electrical Engineering	2	-	40	60	-
2	Audit Course – II (Online)	AC031	English for Research Paper Writing	2	-	40	60	-
		AC032	Disaster Mitigation & Management					
		AC033	Sanskrit for Technical Knowledge					
		AC034	Value Education					
		AC035	Stress Management by Yoga					
		AC036	Personality Development Through Life Enlightenment Skills					
		AC037	Constitution of India					
		AC038	Pedagogy Studies					
3		EE181	Major Project Phase – I Dissertation	-	20*	100		10
TOTAL				4	20	180	120	10
SEMESTER-IV								
1		EE182	Major Project Phase – II Dissertation	-	32*	100	100	16
TOTAL				40	64	1010	940	68

Note:

- Dissertation-II has two parts, CIE - I and CIE - II, at the end of 8th week and 16th week respectively for evaluation of 50 marks each.
- Audit Courses will be offered in ONLINE mode and SEE will be conducted in
- Computer Based Test Mode.
- Research Methodology be offered as an Audit Course for all PG Programs.
- Engineering Research Methodology Workshop will be conducted for one week for Ph.D. scholars.
- Six Core subjects, Five Programme Electives, One Open Elective, Three Laboratory Courses, One Mini project, and One Seminar should normally be completed by the end of semester II.
- Two Audit Courses and Dissertation - I should be completed by the end of semester III.

***The student has to work a minimum of 20 hours/week and 32 hours/week at Dissertation – I and II.**

L – No. of Lecture Contact hours / Week

P – No. of Practical Contact hours /Week

CIE – Continuous Internal Evaluation

SEE – Semester End Evaluation

EE 3101

STATIC CONTROL OF DC DRIVES

Instruction: 3 periods per week

Duration of SEE: 3 hours

CIE: 40 marks
Credits: 3

SEE: 60 marks

Course Objectives

- To understand the operation and performance characteristics of various converters such as Semi Converters, Full converters, Dual converters and choppers for control of separately excited and self-excited DC Motors.
- To understand the power factor improvement methods of single phase and three phase converters.
- To understand the closed loop control of DC motors.

Course Outcomes

After the completion of this course, students will be able to:

1. Identify and Analyze Single phase and three phase semi and full converters fed DC Motors to achieve efficient performance for various application.
2. Analyze Power factor Improvement methods for Single phase and three phase semi and full converters fed DC Motors for various application.
3. Identify and Analyze Dual Converter fed DC Motors to achieve Motoring and Braking operation.
4. Identify and Analyze Various Choppers fed DC Motors to achieve Motoring and Braking operation. Design Input filter for Chopper.
5. Analyze and Design closed loop control of DC Drives

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	-	2
CO2	3	-	3	-	-	2
CO3	3	-	3	-	-	2
CO4	3	-	3	-	-	2
CO5	3	-	3	-	-	2

UNIT I

Single Phase Drives: Performance parameters, Operation of Full converter and Semi – converter fed separately excited D.C. motors and D.C. series motors, Speed-torque characteristics, Performance characteristics, Comparison, Three Phase Drives, Principle and operation.

UNIT II

Power Factor Improvement: Extinction angle control, Symmetrical angle control, Pulse Width Modulation control, Sequence control of single-phase series converters, Full converter and Semi-converter, Sequence control of three phase series converters with shifted voltages.

UNIT III

Dual Converter Drives: Ideal dual converter and Firing control scheme, non-ideal dual converter – Without circulating Current, Control strategies, with circulating current – Closed loop system, Dual mode dual converter, PWM Control, Reversible drives – Armature current reversal and Field current reversal.

UNIT IV

Chopper Drives: One quadrant, two quadrant choppers and four quadrant d.c drives, Analysis, Design of input filter, Multiphase choppers, Dynamic braking and Regenerative braking of phase-controlled drives and chopper drives.

UNIT V

Closed Loop Control: Single phase D.C. drive with dynamic braking, Three-phase dual converter reversible drive, Speed control with inner current loop & field weakening, Phase locked loop control, Microcomputer control.

References

1. Sen PC, “*Thyristor D.C Drives*”, John Wiley, 1981.
2. Singh M.D and Khanchandani K.B, *Power Electronics*, Tata McGraw Hill, 1998.
3. Sen P.C, *Power Electronics*, Tata McGraw Hill Pvt. Ltd., New Delhi.
4. G.K.Dubey, *Power Semi-Converter Controlled Drives*, Prentice Hall, Eaglewood, Cliffs,1989.

EE 3102

MACHINE MODELING AND ANALYSIS

Instruction: 3 periods per week

CIE: 40 marks

Credits: 3

Duration of SEE: 3 hours

SEE: 60 marks

Course Objectives

- To provide knowledge about the fundamentals of magnetic circuits, energy, force, torque and theory of transformation of three phase variables to two phase variables
- To analyze the steady state and dynamic state operation of DC machine through mathematical modeling and simulation in digital computer.
- To analyze the steady state and dynamic state operation of three-phase induction machines and three-phase synchronous machines using transformation theory based mathematical modeling and digital computer simulation.
- To analyze the linearization of Induction and synchronous machines

Course Outcomes

After the completion of this course, students will be able to:

1. Develop models for linear and nonlinear magnetic circuits
2. Determine the developed torque in an electrical machine using the concepts of field Energy and co-energy and determine the dynamic model of a DC machine
3. Determine the dynamic model of an induction machine, instantaneous torque developed in an induction Machine, study control strategies such as vector control and direct torque control
4. Determine the torque developed in a salient pole synchronous machine using the Park's transformation and identify contribution of saliency torque- damping and excitation torque
5. Obtain Linearized equations for Induction and synchronous machines

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	-	2
CO2	3	-	3	-	-	2
CO3	3	-	3	-	-	2
CO4	3	-	3	-	-	2
CO5	3	-	3	-	-	2

UNIT-I

Basic Principles for Electric Machine Analysis: Magnetically coupled circuits, Electromechanical energy conversion, Basic Two pole DC Machine – primitive 2 axis machine – Voltage and Current relationship – Torque equation.

Theory of DC Machines: Mathematical model of separately excited DC Motor, DC Series Motor, DC shunt motor and D.C. Compound Motor in state variable form – Transfer function of the motor.

UNIT II

Reference Frame Theory: Equations of transformation - Change of variables, Stationary circuit variables Transformed to the Arbitrary Reference Frame, commonly used reference frames, Transformation between reference frames, Transformation of a balanced set, Balanced steady state phasor Relationships, Balanced steady state equations, Variables observed from various frames.

UNIT III

Theory of Symmetrical Induction Machines: Voltage and torque equations in machine variables, Equations of transformation for Rotor circuits, Voltage and torque equations in arbitrary reference frame variables, Analysis of steady state operation- state-space model of induction machine in ‘d-q’ variables, Free Acceleration Characteristics, Dynamic Performance-during sudden changes in load-during a 3 phase fault at the machine terminals.

UNIT IV

Theory of Synchronous Machines: Voltage and Torque equations in machine variables, Stator Voltage equations in Arbitrary Reference Frame Variables, Voltage Equations in Rotor Reference Frame Variables: park’s Equations, Torque Equations in Substitute Variables, Analysis of steady state operation, Dynamic performance - During sudden changes in Input Torque - During a 3 phase fault at the machine terminals.

UNIT V

Linearized Machine Equations: Introduction, Machine equations to be linearized Induction machine, Synchronous machine. Linearized machine equations-Induction machines, Synchronous machines. Small-displacement stability-Eigen values, Eigen values of typical Induction machines and synchronous machines.

References

1. Paul C. Krause, Oleg Wasynczuk, Scott D. Sudhoff, “*Analysis of Electric Machinery and drive systems*” John Wiley and Sons, 2 Edition, 2006
2. C.V. Jones, “*Unified Theory of Electrical Machines*” Butterworths Publishers.
3. P.S. Bhimbra, “*Generalized Theory of Electrical Machines*”, Khanna publishers, 2002.
4. J. Meisel, “*Principles of Electromechanical Energy Conversion*” McGraw Hill, 1966.

EE 3103

CONTROL OF ELECTRIC DRIVES

Instruction: 3 periods per week
CIE: 40 marks
Credits: 3

Duration of SEE: 3 hours
SEE: 60 marks

Course objectives

- Understand the concepts of development of control circuits, remote control and electric interlocking in an industry
- Understand the construction and operation of various control components for the control circuits
- Understand the development of control circuits for various operations of both DC and AC machines.
- To understand the procedure for trouble shooting of circuits
- To understand the driver circuits for step motor

Course Outcomes

After the completion of this course, students will be able to:

1. Develop the semi-automatic and automatic control of modern machinery.
2. Know the various protection equipment like MCCB, MCB, Relays, Timers and Switches.
3. Develop control circuits for control of three phase induction motors.
4. Understand the Manual, Timed Semi-Automatic and automatic starters for control of Synchronous motors.
5. Develop and trouble shoot the driver circuits for stepper motors.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	-	2
CO2	3	-	3	-	-	2
CO3	3	-	3	-	-	2
CO4	3	-	3	-	-	2
CO5	3	-	3	-	-	2

UNIT I

Introduction of Electrical Control of Machines: Manual control – Magnetic control – Semi-automatic and Automatic control of Modern machinery – Development of Control circuits–Two wire and Three wire control – Remote control – Interlocking of drives – Control circuit components –Symbols for control components–Fuses, Switches and Fuse Switch units.

UNIT II

Protection of motors: Moulded-Case Circuit Breaker (MCCB) and Miniature Circuit Breaker (MCB) – Contactors – Types of contactors – Contactor ratings, Relays – D.C Series current relay – Frequency responsive relay – Latching relay – Over load relays – Bimetallic Thermal over load relay – time delay relay (Timers) – Motor drivers Electronic timer – Phase failure relay – Push button switches – Types, Limit switch – Float switch.

UNIT III

Control of Three-Phase Induction Motors: Motor current at start and during acceleration – Automatic starters – Increment Resistor type starter – Automatic Autotransformer starter – Open circuit and closed-circuit transition – Part winding motor starters Two step and Three step starting – Automatic Star-Delta starters Open circuit and closed circuit transition – Starters for multi-speed motors. Starters for Wound rotor motors – Control circuit using contactor and flux delay relays.

UNIT IV

Control of Synchronous Motors: Manual Push button synchronizing Starter, Timed Semi-Automatic Synchronizing, Automatic Starter using Polarised Field Frequency Relay.

Control of D.C motors: Principles of acceleration – Types of starters for automatic acceleration – Control circuits for DCL, Current limit acceleration starters – Reviewing of D.C motors – Control circuit for direct reversing and forward stop reverse operation – Jogging operation of D.C motor – Control circuits for braking action.

UNIT V

Control of stepper motors: Control circuit for Stepper motor – Block diagram of a typical step motor control – Types of drive circuits – simple power drive circuit – L/R drive Bi-level drive – Chopper drive – Linear constant current drive – Bipolar drives for Stepper motor – H type and L/R type bipolar drives – Bipolar Chopper drives. Trouble shooting in control circuits – Trouble spots –General procedure for troubleshooting.

References

1. Bhattacharya S.K and Brijinder Singh, *Control of Electrical Machines*, New Age International Publishers, New Delhi, 1996.
2. Athani V.V., *Stepper Motors — Fundamentals, Applications and Design*, New Age International Publishers, New Delhi, 1997.

EE 3111

SPECIAL ELECTRICAL MACHINES

Instruction: 3 periods per week
CIE: 40 marks
Credits: 3

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- To understand the concepts and control strategies of permanent magnet synchronous motors and Brushless DC motors.
- To study the operating principles and control methods of switched reluctance motors.
- To introduce the concepts and control of different types of stepper motors and its applications.
- To analyze the working of linear induction and linear synchronous machines

Course Outcomes

After the completion of this course, the students shall be able to:

1. Optimally design magnetics required in special machines-based drive systems.
2. Develop new control strategies open and closed loop control for different types of special machines.
3. Design and conduct experiments towards research and to solve practical problems
4. Develop and analysis of the controllers for special electrical machine.
5. Analyze and Design Power converters and control techniques for control of special machines.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	-	2
CO2	3	-	3	-	-	2
CO3	3	-	3	-	3	2
CO4	3	-	3	-	3	2
CO5	3	-	3	-	-	2

UNIT I

Stepper Motors: Constructional features, Principle of operation, Variable Reluctance (VR) stepping motor-Single Stack, Multi-Stack, Permanent Magnet Step motor, Hybrid Step Motor, Torque Equation Open Loop Drive, Open loop and closed loop control of Step Motor, Applications.

UNIT II

Switched Reluctance Motors: Constructional features, Principle of Operation, Torque equation, Torque-speed characteristics, Power Converter for SR Motor-Asymmetrical converter, DC Split converter, Control of SRM, Rotor Position sensors, Current Controllers, Applications.

UNIT III

Permanent Magnet Synchronous Motor: Permanent magnets and their characteristics, Machine Configurations-SPM, SIPM, IPM and Interior PM with circumferential, Sensorless control, Applications.

UNIT IV

Brushless DC Motor: Construction, Principle of Drive operation with inverter, Torque speed Characteristics, Closed loop control, Sensorless control, Applications.

UNIT V

Linear Induction Motors and Linear Synchronous Motors: Linear induction motor, Construction details, LIM Equivalent Circuit, Steps in design of LIM, Linear Synchronous Motor: Principle and Types of LSM, LSM Control, Applications.

References

1. R.Krishnan, *Electric Motor Drives*, Pearson, 2007
2. B.K.Bose, *Modern Power Electronics and AC Drives*, PHI, 2005
3. Venkataratnam, *Special electrical Machines*, University Press, 2008
4. E.G.Janardanan, *Special Electrical Machines*, PHI, 2014
5. T.J.E.Miller, *Brushless Permanent Magnet and Reluctance Motor Drive*, Clarendon Press, Oxford, 1989

EE3112

NEURAL NETWORKS AND FUZZY LOGIC

Instruction: 3 periods per week

CIE: 40 marks

Credits: 3

Duration of SEE: 3 hours

SEE: 60 marks

Course Objectives

- 1. To introduce the Neural & fuzzy intelligence
- 2. To study the different models in ANN and their applications
- 3. To familiarize different learning concepts and algorithms of Neural Networks
- 4. To familiarize the fundamentals of Fuzzy Logic required to apply Fuzzy Logic in control, pattern recognition and Planning and Diagnosis.
- 5. To give exposure to Neural Network and Fuzzy Logic applications in Electrical Engineering.

Course Outcomes

After the completion of this course, students will be able to:

1. Explain the basic concepts in Fuzzy and Neural intelligence.
2. Understand the different Neural network models
3. Understand different learning methods and algorithms of Neural Networks.
4. Apply the fuzzy concepts in the areas of control, pattern recognition and Planning and Diagnosis
5. Apply the knowledge Neural Networks and Fuzzy Logic to different power systems problems.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	2	2
CO2	3	-	3	-	2	2
CO3	3	-	3	-	2	2
CO4	3	-	3	-	2	2
CO5	3	-	3	-	2	2

UNIT I

Neural and Fuzzy Intelligence: Fuzziness as multi-valence - Bivalent paradoxes as fuzzy midpoints, Sets as points in cubes - Subset hood and probability, The dynamical system approach to machine intelligence, Brain as a dynamical system – Neural networks as trainable dynamical system, Intelligent behavior as adaptive model free estimation, Generalization and creativity - Learning as change-Rules vs. principles - Symbolic vs. numeric processing, Structured numerical estimators

UNIT II

Neural Network Theory: Neurons as functions - Signal monotonicity Biological activities and signals, Neuron fields - Neuronal dynamic systems - Common signal, functions - Pulse coded signal functions, Additional neuron dynamics – Additive neural feedback - Additive activation models Bivalent BAM theorem, Hopfield model.

UNIT III

Synaptic Dynamics: Unsupervised learning - Learning laws, Signal Hebbian learning- Competitive learning, Differential Hebbian learning - Supervised learning, The perceptrons – LMS algorithm, Back propagation algorithm - AVQ algorithm, Global stability of feedback neural networks.

UNIT IV

Fuzzy Logic: Fuzzy sets and systems-Geometry of fuzzy sets, Fuzzy entropy theorem-Entropy subset - Hood theorem, Fuzzy& neural function estimators-FAM system Architecture, Uncertainty and estimation - Types of uncertainty – Measure of fuzziness - Classical measures of uncertainty, Measures of dissonance - Confusion and non-specificity. Fuzzy logic structure, Knowledge base defuzzification, Fuzzy logic in control-Pattern recognition–Planning diagnosis

UNIT V

Fuzzy Logic and ANN Applications: Fuzzy logic application to Induction motor speed control, Flux programming efficiency improvement of induction motor drive, pulsating torque compensation. Neural Network applied to Space Vector PWM, Vector controlled drive feedback signal estimation, model identification and adaptive drive control. Neuro-Fuzzy systems, ANN based Fuzzy inference system (ANFIS)

References

1. Bart Kusko, *Neural Networks and Fuzzy System* - Prentice Hall of India, 1994.
2. B. Yegnanarayana, *Artificial Neural Networks*, PHI Learning 1994.
3. B.K. Bose, *Modern Power electronics and AC drives*, Prentice Hall PTR, 2002.
4. Timothy J. Ross, *Fuzzy Logic with Engineering Applications*, Wiley.

EE3113

RENEWABLE ENERGY SOURCES

Instruction: 3 periods per week

CIE: 40 marks

Credits: 3

Duration of SEE: 3 hours

SEE: 60 marks

Course Objectives

- To understand the concepts and Importance of renewable energy sources such as solar, wind, biomass, tidal power.
- To make the students understand the advantages and disadvantages of different renewable energy sources
- To be familiar with the technologies used to generate electrical energy, storage and applications

Course Outcomes

After the completion of this course, the students will be able to:

1. Understand the basic principle of operations of renewable energy sources.
2. Understand the applications of renewable energy sources.
3. Understand the technology processes of renewable energy sources.
4. Understand the technology processes of renewable energy sources
5. Study of the applications of renewable energy sources

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	3	2
CO2	3	-	3	-	3	2
CO3	3	-	3	-	3	2
CO4	3	-	3	-	3	2
CO5	3	-	3	-	3	2

Syllabus Contents

UNIT I

Review of Conventional and Non-Conventional energy sources - Need for nonconventional energy sources Types of Non- conventional energy sources – Fuel Cells - Principle of operation with special reference to H₂ / O₂ Cell - Classification and Block diagram of fuel cell systems – Ion exchange membrane cell – Molten carbonate cells - Solid oxide electrolyte cells - Regenerative system- Regenerative Fuel Cell - Advantages and disadvantages of Fuel Cells — Polarization - Conversion efficiency and Applications of Fuel Cells.

UNIT II

Solar energy - Solar radiation and its measurements - Solar Energy collectors –Solar Energy storage systems - Solar Pond - Application of Solar Pond - Applications of solar energy.

UNIT III

Wind energy- Principles of wind energy conversion systems - Nature of wind – Power in the Wind-Basic components of WECS -Classification of WECS -Site selection considerations - Advantages and disadvantages of WECS -Wind energy collectors – Wind electric generating and control systems - Applications of Wind energy Environmental aspects.

UNIT IV

Energy from the Oceans - Ocean Thermal Electric Conversion (OTEC) methods - Principles of tidal power generation -Advantages and limitations of tidal power generation -Ocean waves - Wave energy conversion devices -Advantages and disadvantages of wave energy - Geo-thermal Energy - Types of Geo-thermal Energy Systems - Applications of Geo-thermal Energy.

UNIT V

Energy from Biomass - Biomass conversion technologies / processes – Photosynthesis - Photosynthetic efficiency - Biogas generation - Selection of site for Biogas plant - Classification of Biogas plants - Details of commonly used Biogas plants in India - Advantages and disadvantages of Biogas generation -Thermal gasification of biomass -Biomass gasifiers.

References

1. Rai G.D, *Non-Conventional Sources of Energy*, Khandala Publishers, New Delhi, 1999.
2. M.M.El-Wakil, *Power Plant Technology*. McGraw Hill, 1984.

EE3114

POWER ELECTRONIC APPLICATIONS TO POWER SYSTEMS

Instruction: 3 periods per week
CIE: 40 marks
Credits: 3

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- To understand the issues involved in existing Power Transmission system
- To be familiar with the Techniques to overcome the problems associated with AC Power Transmission system
- To Understand the control of active and reactive power control using Power electronic converters

Course Outcomes

After the completion of this course, the students shall be able to:

1. Know the application of FACTS devices in Power Transmission system.
2. Study and apply the power transmission schemes – HVDC Transmission
3. Implement the control circuits based on the Controlling parameters of HVDC system
4. Select appropriate FACTS controllers depending on application.
5. Understand various types of HVDC systems and their advantages.

Syllabus Contents

UNIT I

Facts concepts: Reactive power control in electrical power transmission, principles of conventional reactive power compensators. Introduction to FACTS, flow of power in AC parallel paths, meshed systems, basic types of FACTS controllers, definitions of FACTS controllers, brief description of FACTS controllers.

UNIT II

Static shunt and series compensators: Shunt compensation - objectives of shunt compensation, methods of controllable VAR generation, static VAR compensators - SVC, STATCOM, SVC and STATCOM comparison. Series compensation - objectives of series compensation, thyristor switched series capacitors (TCSC), static series synchronous compensator (SSSC), power angle characteristics, and basic operating control schemes.

UNIT III

Combined Compensators: Unified power flow controller (UPFC) - Introduction, operating principle, independent real and reactive power flow controller and control structure. Interline power flow controller (IPFC), Introduction to Active power filtering, Concepts relating to Reactive power compensation and harmonic current compensation using Active power filters.

UNIT IV

HVDC transmission: HVDC Transmission system: Introduction, comparison of AC and DC systems, applications of DC transmission, types of DC links, Layout of HVDC Converter station and various equipment. HVDC Converters, analysis of bridge converters with and without overlap, inverter operation, equivalent circuit representation of rectifier and inverter configurations

UNIT V

Control of HVDC system: Principles of control, desired features of control, converter control characteristics, power reversal, Ignition angle control, current and extinction angle control. Harmonics-introduction, generation, ac filters and dc filters. Introduction to multiterminal DC systems and applications, comparison of series and parallel MTDC systems.

References

1. Song, Y.H. and Allan T. Johns, 'Flexible AC Transmission Systems (FACTS)', Institution of Electrical Engineers Press, London, 1999.
2. Hingorani, L.Gyugyi, 'Concepts and Technology of Flexible AC Transmission System', IEEE Press New York, 2000 ISBN –078033 4588.
3. Padiyar, K.R., 'HVDC transmission systems', Wiley Eastern Ltd., 2010.
4. Mohan Mathur R. and Rajiv K.Varma, 'Thyristor - based FACTS controllers for Electrical transmission systems', IEEE press, Wiley Inter science , 2002.
5. Padiyar K.R., 'FACTS controllers for Transmission and Distribution systems' New Age International Publishers, 1st Edition, 2007.
6. Enrique Acha, Claudio R.Fuerte-Esqivel, Hugo Ambriz-Perez, Cesar Angeles Camacho 'FACTS –Modeling and simulation in Power Networks' John Wiley & Sons, 2002.

EE 3121

RELIABILITY ENGINEERING

Instruction: 3 periods per week
CIE: 40 marks
Credits: 3

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- To comprehend the basics of probability distributions & reliability models.
- To model systems with series-parallel block diagrams and state-space diagrams and to understand time dependent and limiting state probabilities using Markov models.
- To understand multi-mode failures of electrical & electronic circuits and their effect on reliability & availability.
- To understand reliability & availability models for generation, transmission and distribution systems and evaluate critical indices.

Course Outcomes

After the completion of this course, the students shall be able to:

1. Able to relate the probability concepts and distributions in reliability engineering studies
2. Able to draw reliability logic diagram and state-space diagram of engineering systems to evaluate reliability and availability
3. Apply multi-mode failures in electrical and electronic circuits
4. Model generation and transmission systems for reliability studies.
5. Evaluate various reliability indices related to generation, transmission and distribution systems

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	-	1
CO2	3	-	3	-	-	1
CO3	3	-	3	-	-	1
CO4	3	-	3	-	-	1
CO5	3	-	3	-	-	1

UNIT I

Discrete & Continuous random variables – Binomial, Exponential & Weibull distributions – Causes of failure – Failure rate & Failure density – Bath tub curve – Reliability & MTTF – Maintainability & Availability – MTBF & MTTR – Reliability block diagram – Series & Parallel systems – Conditional probability - Minimal Cutset & Tie-set methods

UNIT II

Continuous Markov models – State space diagram - Reliability models of single unit, two unit & standby systems – Reliability & Availability models with repair – Frequency of failures – State transition matrix and estimation of MTTF.

UNIT III

Multi-mode failures - Short circuit & open circuit failures - Resistors & capacitors in series & parallel - Diodes & MOSFETs in series & parallel - Quad system - Reliability Prediction - MIL standards - Parts count technique - Parts stress technique - Reliability, Availability and MTTF evaluation of Power electronic circuits & Drive Systems

UNIT IV

Outage definitions – Markov model of Generating plant with identical and non-identical units – Capacity Outage probability table – Cumulative frequency – LOLE & LOEE – Composite Generation & Transmission systems - Radial configuration – Conditional probability approach

UNIT V

Customer oriented, load oriented & energy oriented indices of distribution system – Application to radial systems – Effects of lateral distributor protection, disconnects, protection failures & transferring loads – Parallel & Mesh networks – Dual transformer feeder – Approximate, Network reduction & FMEA methods

References

1. Roy Billinton, R.N. Allan, 'Reliability Evaluation of Engineering Systems', Springer International Edition, Plenum Press, New York, 1992
2. E. Balaguruswamy, 'Reliability Engineering', Tata McGraw Hill Education Pvt. Ltd., 2012
3. Charles E. Ebeling, 'An Introduction to Reliability and Maintainability Engineering', McGraw Hill International Edition, 1997
4. L. Umanand, 'Power Electronics: Essentials & Applications', Wiley, 2009
5. Roy Billinton, R.N. Allan, 'Reliability Evaluation of Power Systems', Springer, 1st Edition, Plenum Press, New York, 1996.

EE 3122

ADVANCED OPTIMIZATION TECHNIQUES

Instruction: 3 periods per week
CIE: 40 marks
Credits: 3

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- To understand the concepts of single variable and multivariable optimization with and without constraints
- To make the students understand about linear and nonlinear optimization problems.
- To make the students understand about Evolutionary computational techniques

Course Outcomes

After the completion of this course, the students shall be able to:

- Formulate practical problems to mathematical models and solve single, multivariable methods with and without constraints
- Solve linear optimization problems
-
- Solve linear and nonlinear optimization problems
- Understand different Metaheuristics Algorithms
- Solve Multi-objective with pareto optimality

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	2	-	-	-
CO2	3	-	3	-	-	-
CO3	3	-	3	-	-	-
CO4	2	-	3	2	-	2
CO5	2	-	3	2	-	2

UNIT I

Classical Optimization techniques: Introduction to optimization and design optimization, optimum design problem formulation, Single variable optimization- Multivariable optimization with and without constraints – Multi variable optimization with inequality constraints – Solution by Lagrangian multipliers - Kuhn-Tucker conditions.

UNIT II

Linear Programming: Formulation and standard form of LP problem, Basic definitions and theorems – Solution of a system of linear simultaneous equations – simplex method and its algorithm – Revised simplex method – Big-M method – Duality in LP and primal dual relations – Dual simplex method.

UNIT III

Non-Linear Programming: One dimensional minimization methods – Introduction – Elimination methods – Unrestricted search, Exhaustive search, Dichotomous search, Fibonacci methods. Unconstrained optimization techniques- Univariate and Powell's pattern search method, steepest descent method.

UNIT IV

Metaheuristics Algorithms 1:

Science based Algorithms: Simulated annealing - metropolis criterion - algorithm - pseudo code- examples.

Human based Algorithms: Tabu search- different strategies - Algorithm- pseudo code-examples.

Evolution based Algorithms: Genetic algorithms – binary encoding, real encoding, permutation encoding - different selection process - crossover for different encodings - mutation for different encodings - Elitism - pseudo code -Genetic Algorithm examples.

UNIT V

Metaheuristics Algorithms 1:

Swarm intelligence-based algorithms: Particle Swarm Optimization - exploration - exploitation - parameters of PSO - personal best - global best-Algorithm - pseudo code - examples- Limitations of original PSO - PSO variants.

Introduction to Multi-objective optimization: Need of multi-objective approach-Pareto optimality - examples - Non dominated Sorting Genetic algorithm II- Algorithm - pseudo code - applications.

References

1. Engineering Optimization, Theory and Practice - Singiresu S. Rao, S. S. Rao – Fourth edition – New Age Internationals – 2009.
2. Introduction to Optimum design, Jasbir S. Arora, - Third Edition – Elsevier – 2013.
3. Optimization methods for Engineers, N.V.S. Raju – PHI – 2014.
4. Introduction to Genetic Algorithms, S.N.Sivanandam, S.N Deepa – Springer – 2013.
5. Search and Optimization by Metaheuristics-Techniques and algorithms inspired by nature, Ke-LinDu, M.N.S Swamy - Springer international publishing - 2016
6. Yang, Xin-She, Nature-Inspired Metaheuristic Algorithms, 2010/07/25
7. Link: https://www.researchgate.net/publication/235979455_Nature-Inspired_Metaheuristic_Algorithms
8. https://www.researchgate.net/publication/228346477_Tabu_Search
9. Alhammadi, H. Y., & Romagnoli, J. A. (2004). Process design and operation. Computer Aided Chemical Engineering, 264–305.
10. Ant Colony Optimization for Mixed-Variable Optimization Problems: IEEE Transactions on evolutionary computation, vol. 18, no. 4, august 2014.

EE 3123

DIGITAL CONTROL OF POWER ELECTRONICS

Instruction: 3 periods per week

CIE: 40 marks

Credits: 3

Duration of SEE: 3 hours

SEE: 60 marks

Course Objectives

- To understand the concept of architecture and peripheral modules of microcontroller, digital signal processors and field programmable gate arrays
- To prepare the students for acquiring the knowledge of Implementing digital processor-based control systems for power electronics
- To know the use of microcontrollers for pulse generation in power converters
- To know the use of field programmable gate arrays for pulse generation in power converters

Course Outcomes

After the completion of this course, students will be able to:

1. Acquire knowledge in CPU details, addressing modes, interrupt structure, hardware multiplier
2. Implement numerical integration methods using digital processor-based control systems.
3. Design interfacing applications based on internal peripheral units of PIC microcontrollers and programming them using MPLAB and PICSTART plus
4. Write programs using DSP and FPGA boards
5. Implement DSP-based electromechanical motion control

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	2	-	2
CO2	3	-	3	2	-	2
CO3	3	-	3	2	2	2
CO4	3	-	3	2	2	2
CO5	3	-	3	2	2	2

*Syllabus
Contents*

UNIT I

Review of microcontrollers, digital signal processors, architecture and Field Programmable Gate Arrays, Data Representation Integers, Fixed and Floating-point numbers, and Characters. PIC Microcontrollers: Overview of PIC family, PIC Architecture, PIC Assembly Language Programming, RISC Architecture in PIC, Introduction to MPLAB IDE and PICSTART plus – Device Programming using MPLAB and PICSTART plus – generation of firing / gating pulses for typical power converters.

UNIT II

Introduction to the C2xx DSP core and code generation, components of the C2xx DSP core, Mapping external devices to the C2xx core, peripherals and Peripheral Interface,

System configuration registers, Memory, Types of Physical Memory, memory Addressing Modes, Assembly Programming using C2xx DSP, Instruction Set, Software Tools. Pin Multiplexing (MUX) and General Purpose I/O Overview, Multiplexing and General Purpose I/O Control Registers.

UNIT III

Enhanced Pulse Width Modulator (ePWM) Module-Time-Base (TB) Submodule, Counter-Compare (CC) Submodule, Action-Qualifier (AQ) Submodule, Dead-Band Generator (DB) Submodule, PWM-Chopper (PC) Submodule, Trip-Zone (TZ) Submodule, Event-Trigger (ET) Submodule, Applications to Power Topologies- Overview of Multiple Modules, Key Configuration Capabilities, Controlling Multiple Buck Converters With Independent Frequencies, Controlling Multiple Buck Converters With Same Frequencies, Controlling Multiple Half H-Bridge (HHB) Converters, Controlling Dual 3-Phase Inverters for Motors (ACI and PMSM), Practical Applications Using Phase Control Between PWM Modules, Controlling a 3-Phase Interleaved DC/DC Converter, Controlling Zero Voltage Switched Full Bridge (ZVSFB) Converter.

UNIT IV

Analog-to-Digital Converter (ADC)- ADC Overview, Operation of the ADC, Auto conversion Sequencer Principle of Operation-Sequential Sampling Mode, Simultaneous Sampling Mode, Uninterrupted Auto sequenced Mode, ADC Clock Prescaler, ADC Registers.

UNIT V

Introduction to Field Programmable Gate Arrays – CPLD Vs FPGA – Types of FPGA, Xilinx XC3000 series, Configurable logic Blocks (CLB), Input/Output Block (IOB) – Programmable Interconnect Point (PIP) – Xilinx 4000 series – HDL programming – overview of Spartan 3E and Virtex II pro FPGA boards- case study.

References

1. PIC16F87X Datasheet 28/40 – pin 8bit CMOS flash Microcontrollers, Microchip technology Inc., 2001. and MPLAB IDE Quick start guide, Microchip technology Inc., 2007.
2. John B. Peatman, ‘Design with PIC Microcontrollers’, Prentice Hall, 2003.
3. MykePredko, ‘Programming and customizing the PIC Microcontroller’ Tata McGraw-Hill, 3rd Edition, 2008.
4. Hamid.A.Toliyat and Steven G.Campbell‘DSP Based Electro Mechanical Motion Control’ CRC Press New York , 2004
5. XC 3000 series datasheets (version 3.1). Xilinx,Inc.,USA, 1998
6. XC 4000 series datasheets (version 1.6). Xilinx,Inc.,USA, 1999
7. Wayne Wolf,” FPGA based system design “, Prentice hall, 2004

EE3302

POWER ELECTRONIC CONVERTERS FOR RENEWABLE ENERGY

Instruction: 3 periods per week
CIE: 40 marks
Credits: 3

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- To learn the types of renewable sources such as Wind, solar, hydro and geothermal sources.
- To understand the principle and operation of various DC-DC converters.
- To understand the concepts of grid connected inverters and grid connected issues.
- To understand the principle of operation of doubly fed induction generator with rotor side converter topologies.

Course Outcomes

After the completion of this course, students will be able to:

1. Understand P-V & I-V characteristics of solar PV and different MPPT Techniques.
2. Understands the maximum power point tracking for different Converters.
3. Analyze the grid connection issues and different types of transformer less topologies.
4. Understand the P-V and I-V characteristics and power extraction of wind energy systems.
5. Analyze the different types of wind generators for wind power applications.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	2	3	2
CO2	3	-	3	2	3	2
CO3	3	-	3	2	3	2
CO4	3	-	3	2	3	2
CO5	3	-	3	2	3	2

*Syllabus
Contents*

UNIT I

Introduction to renewable sources: world energy scenario, Wind, solar, hydro, geothermal, availability and power extraction. Introduction to solar energy: Photovoltaic effect, basics of power generation, P-V & IV characteristics, effect of insolation, temperature, diurnal variation, shading, Modules, connections, ratings, Power extraction (MPP) tracking and MPPT schemes; standalone systems, grid interface, storage, AC-DC loads.

UNIT II

DC-DC converters for solar PV: buck/boost/buck-boost /flyback /forward/cuk, bidirectional converters, Interleaved and multi-input converters.

UNIT III

Grid connected Inverters: 1ph, 3ph inverters with & without transformers, Heric, H6, Multilevel Neutral point clamp, Modular multilevel, CSI; Control schemes: unipolar, bipolar, PLL and synchronization, power balancing / bypass, Parallel power processing; Grid connection issues: leakage current, Islanding, harmonics, active/reactive power feeding, unbalance.

UNIT IV

Introduction to wind energy: P-V, I-V characteristic, wind power system: turbine generator-inverter, mechanical control, ratings; Power extraction (MPP) and MPPT schemes. Generators for wind: DC generator with DC to AC converters; Induction generator with & w/o converter.

UNIT V

Synchronous generator with back to back controlled/ uncontrolled converter; Doubly fed induction generator with rotor side converter topologies; permanent magnet based generators. Battery: Types, charging discharging. Introduction to AC and DC micro grids.

References

1. SudiptaChakraborty, Marcelo G. Simes, and William E. Kramer. Power Electronics for Renewable and Distributed Energy Systems: A Sourcebook of Topologies, Control and Integration. Springer Science & Business, 2013.
2. Nicola Femia, Giovanni Petrone, Giovanni Spagnuolo, Massimo Vitelli, Power Electronics and control for maximum Energy Harvesting in Photovoltaic Systems, CRC Press, 2013.
3. Chetan Singh Solanki, Solar Photovoltaics: fundamentals, Technologies and Applications, Prentice Hall of India, 2011.
4. N. Mohan, T.M. Undeland & W.P. Robbins, Power Electronics: Converter, Applications & Design, John Wiley & Sons, 1989
5. Muhammad H. Rashid, Power Electronics: Circuits, Devices, and Applications, Pearson Education India, 2004
6. E. Guba, P. Sanchis, A. Ursa, J. Lopez, and L. Marroyo, Ground currents in single phase transformerless photovoltaic systems, Progress in Photovoltaics: Research and Applications, vol. 15, no. 7, 2007.
7. Remus Teodorescu, Marco Liserre, Pedro Rodriguez, Grid Converters for Photovoltaic and Wind Power Systems, John Wiley and Sons, Ltd., 2011.
8. Ali Keyhani, Design of Smart Power Grid Renewable Energy Systems, WileyIEEE Press, 2011.

EE 3131

INDUSTRIAL CONTROLLERS

Instruction: 3 periods per week
CIE: 40 marks
Credits: 3

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- To develop knowledge about 8051 Micro controller and its assembly language programming.
- To be familiarize with LF2407 DSP controller, its architecture, programming, GPIOs, Interrupts, ADC, Event Managers and learn how to produce PWM waveforms.
- To be aware of Programmable Logic Controller and how to develop ladder programs.

Course outcomes: After the completion of this course, the students shall be able to:

1. Understand the working of 8051 micro controller architecture and its programming.
2. Understand the functioning of Digital Signal Processor in LF2407 controller and programming of TMS320C2xx processor.
3. Understand the concept of GPIO, interrupts, ADC and programming them.
4. Use different resources available in even manager in the application of Electro mechanical motion control such as dead band generation, PWM generation, QEP circuitry etc.
5. Develop ladder programs for different industrial PLC applications.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	2	-	2	-	-	1
CO2	3	-	3	-	-	2
CO3	3	-	3	-	-	2
CO4	3	-	3	-	-	2
CO5	2	-	3	-	-	2

UNIT I

8051 Micro controller: Architecture, memory organization, timing and control, parallel ports, timer/counters, serial port and interrupts. Addressing modes and instruction set of 8051 micro controller and its usage.

UNIT II

TMSLF2407 DSP Controller: Introduction, brief introduction to peripherals, types of physical memory, software tools.

C2XX DSP CPU and instruction set: C2xx DSP Core and code generation, mapping external devices to the C2xx DSP core and the peripherals, memory, addressing modes, assembly programming using C2xx DSP instruction set.

UNIT III

GPIO functionality: Pin multiplexing (MUX) and GPIO Overview, multiplexing and GPIO control registers.

Interrupts on the TMS320LF2407: Introduction, Interrupt Hierarchy and its Control Registers.

UNIT IV

ADC: Overview, Operation and programming modes.

Event managers: Overview, Interrupts, Timers, Compare Units, Capture units and QEP circuitry PWM Signal Generation with Event Managers.

UNIT V

Programmable Logic Controller (PLC) Basics: Definitions and history of PLCs – Advantages and disadvantage of PLC – overall PLC Systems, CPUs and Programmer/ Monitors – Programming procedures – programming equipment – Programming formats Ladder diagrams, Basic PLC programming and Basic PLC functions: Programming on / off inputs to produce on / off outputs, PLC programming examples.

References

1. Kenneth J. Ayala, The Micro Controllers - Architecture, Programming & Applications, Penram International Publishing (India).
2. Hamid A Toliyat, DSP based Electromechanical Motion Control, Steven Campbell 2004, CRC Press.
3. John W. Webb and Roland A. Reis, Programmable Logic Controllers, Prentice Hall India Ltd., Fifth edition, 2003.

EE 3132

ADVANCED MICROPROCESSORS

Instruction: 3 periods per week
CIE: 40 marks
Credits: 3

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- To understand the interfacing circuits for various peripheral applications
- To illustrate the architecture of processor of 8086
- To introduce to the programming and interfacing techniques of 8086
- Apply knowledge of soft skill and other resources to design automated system with programming module
- To introduce the architecture of advanced data processor

Course Outcomes

After the completion of this course, the students shall be able to:

1. Design interfacing circuits of various devices with the microprocessor
2. Outline the architecture of 8086 processor
3. Develop programming skills in assembly language.
4. Understand the impact of microprocessor-based system in process of automation.
5. Be familiar with the architecture and operation of processor

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	-	2
CO2	3	-	3	-	-	2
CO3	3	-	3	-	-	2
CO4	3	-	3	-	-	2
CO5	3	-	3	-	-	2

Syllabus
Contents

UNIT I

Review of Basic I/O Interfaces: Programmable Interval Timer 8253 – Programmable peripheral Interlace 8255 – Programmable Interrupt Controller 8259 Microprocessor 8085 applications.

UNIT II

8086 Architecture: CPU Architecture Machine language instructions – Instruction execution – Timing.

UNIT III

Assembler Language Programming: Incorporating Data Transfer –Branch Arithmetic -Loop - NOP and HLT - Flag manipulation, Logical Shift and Rotate Instructions – Directives and Operators.

UNIT IV

Modular Programming: Linking and Relocation –Stacks – Procedures – Interrupts and Interrupt Routines. Byte and String Manipulation: String instruction – REP Prefix –Text Editor – Table translation.

UNIT V

8087 Numeric Data Processor: NDP –Data types –Processor architecture –Instruction set.

References

1. Liu, Gibson, Microcomputer Systems The 8086/8088 Family, Prentice Hall India, 1986.
2. Ghosh, Sridhar, 0000-8085 introduction to Microprocessors, Prentice HallIndia, 1991.

EE3133

PROGRAMMABLE LOGIC CONTROLLERS

Instruction: 3 periods per week
CIE: 40 marks
Credits: 3

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- To provide the knowledge of different components used in PLCs such as processor, input/output devices and programmer monitors
- To make the students thorough with ladder programming of PLC.
- To train them how to use timer, counter, register, arithmetic and different conversion systems.
- To give awareness about application of different PLC features in Process control industry and different data handling functions of PLC.

Course Outcomes After the completion of this course, the students shall be able to:

1. Understand different components of PLC.
2. Construct ladder diagrams for different industry applications.
3. Deal with applications like timer/counter, registers etc.
4. Understand the utility of different features of PLC in process industry.
5. Use data handling function in PLC programming.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	-	1
CO2	3	-	3	-	-	1
CO3	3	-	3	-	-	1
CO4	3	-	3	-	-	1
CO5	3	-	3	-	-	1

UNIT I

PLC Basics: Definition and History of PLC - PLC advantages and disadvantages - Over all PLC Systems - CPUs and Programmer Monitors - PLC input and output models - Printing PLC Information- Programming Procedures – Programming Equipment - Programming Formats- Proper Construction of PLC Diagrams – Devices to which PLC input and output modules are connected - Input on/off switching devices - Input analog devices - Output analog on/off devices and output analog devices.

UNIT II

Basic PLC Programming: Programming on/off inputs to produce on/off outputs - PLC input instructions - Outputs - Operational procedures - Contact and coil input/output programming examples - Relation of digital gate logic contact / coil logic - PLC programming and conversion examples - Creating ladder diagrams from process control descriptions - Sequence listings - Large process ladder diagram constructions.

UNIT III

Basic PLC Functions: General Characteristics of Registers - Module addressing - Holding registers - Input registers - output registers - PLC timer functions – examples of timer functions. Industrial applications - PLC counter functions.

UNIT IV

Intermediate Functions: PLC Arithmetic functions - PLC additions and subtractions - The PLC repetitive clock - PLC Multiplications, Division and Square Root – PLC trigonometric and log functions - Other PLC arithmetic functions - PLC number comparison functions. PLC basic comparison functions and applications – Numbering systems and number conversion functions - PLC conversion between decimal and BCD-Hexadecimals numbering systems.

UNIT V

Data Handling Functions: The PLC skip and master control relay functions – Jump functions - Jump with non return - Jump with return. PLC data move Systems – The PLC functions and applications. PLC functions working with bits - PLC digital bit functions and applications - PLC sequence functions - PLC matrix functions.

References

1. John W. Weff, Ronald A. Reis, *Programmable Logic Controllers*, Prentice Hall of India Private Limited, Fifth edition, 2003.

EE3134

DIGITAL SIGNAL PROCESSING

Instruction: 3 periods per week
CIE: 40 marks
Credits: 3

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- To gain knowledge about discrete time signal and systems; their representation, operations and properties.
- To understand the importance of frequency domain representation of discrete time signals and calculating DTFT, DFT and FFT.
- To learn to represent discrete time signals and systems in Z-domain and finding solution of difference equations using z-transform.
- To design IIR and FIR filters.
- To familiarize with the digital signal processor TMS320C5X

Course Outcomes

After the completion of this course, the students shall be able to:

1. Produce discrete time signals and analyze them and determine discrete time system output for the given discrete time input signals.
2. Determine frequency domain representation DTFT, DFT and FFT.
3. Use z-transforms effectively in the analysis and solutions of discrete time systems.
4. Design IIR and FIR filters.
5. Explain the architecture, memory and peripherals of Digital Signal Processor.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	2	-	2	-	-	-
CO2	2	-	2	-	-	-
CO3	2	-	2	-	-	-
CO4	2	-	2	-	-	-
CO5	2	-	2	-	-	-

Syllabus Contents

UNIT I

Introduction to Digital Signal Processing: Discrete time signals & sequences - Linear shift Invariant systems - Stability and causality- Linear constant coefficient difference equations - Frequency domain representation of discrete time signals and systems.

UNIT II

Discrete Fourier Series: Properties of Discrete Fourier Series - DFS representation of periodic sequences - Discrete Fourier Transforms- Properties of DFT – Linear convolution of sequences using DFT - Computation of DFT - Fast Fourier Transforms (FFT) - Radix-2 decimation in time and decimation in frequency FFT Algorithms inverse FFT.

UNIT III

Applications of Z-Transforms: Solution of difference equations of digital filters - System function - Stability criterion - Frequency response of stable systems - Realization of digital filters - Direct, Canonic, Cascade & Parallel forms.

UNIT IV

IIR Digital Filters: Analog filter approximations - Butterworth and Chebyshev - Design of IIR Digital filters from analog filters - Bilinear transformation method - Step & Impulse invariance techniques - Spectral Transformations. FIR Digital Filters: Characteristics of FIR Digital Filters - Frequency response - Design of FIR filters using Window Techniques.

UNIT V

Introduction to digital signal processors: TMS320C5X architecture – CALU, ARAU, PLU, MMR, on chip memory, on chip peripherals, Digital signal processing applications.

References

1. Proakis & Manolakis, Digital Signal Processing Principles, P Pub. 1994.
2. Sahivahanam, Valtavaraj & Gnanapariya, Digital Sign Processing, TMGH Pub. 2001.
3. Oppenheim & Schaffter, Digital Signal Processing, PHI Pub.
4. S.K.Mitra, Digital Signal Processing, TMH, 1996.

EE3135

PYTHON PROGRAMMING

Instruction: 3 periods per week

CIE: 40 marks

Credits: 3

Duration of SEE: 3 hours

SEE: 60 marks

Course Objectives

The main objective is to teach Computational thinking using Python.

- To know the basics of Programming
- To convert an algorithm into a Python program
- To construct Python programs with control structures.
- To structure a Python Program as a set of functions
- To use Python data structures-lists, tuples, dictionaries.
- To do input/output with files in Python.
- To construct Python programs as a set of objects.

Course Outcomes

After completion of this course, the students shall be able to:

1. Develop algorithmic solutions to simple computational problems.
2. Develop and execute simple Python programs.
3. Develop simple Python programs for solving problems.
4. Structure a Python program into functions.
5. Represent compound data using Python lists, tuples, and dictionaries.
6. Read and write data from/to files in Python Programs

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	2	-	2	-	-	-
CO2	2	-	2	-	-	-
CO3	2	-	2	-	-	-
CO4	2	-	2	-	-	-
CO5	2	-	2	-	-	-

UNIT-I

Introduction to Computing and Problem-Solving: Fundamentals of Computing — Computing Devices — Identification of Computational Problems — Pseudo Code and Flowcharts — Instructions — Algorithms — Building Blocks of Algorithms.

Introduction to Python Programming: Python Interpreter and Interactive Mode- Variables and Identifiers — Arithmetic Operators — Values and Types — Statements, Reading Input, Print Output, Type Conversions, The type () Function and Is Operator, Dynamic and Strongly Typed Language.

Control Flow Statements: The if, The if...else, The if...else if...else Decision Control Statements, Nested if Statement, The while Loop, The for Loop. The continue and break Statements.

UNIT-II

Functions: Built-In Functions, Commonly Used Modules, Function Definition and Calling the Function, The return Statement and void Function, Scope and Lifetime of Variables, Default Parameters, Keyword Arguments, and Command Line Arguments.

Strings: Creating and Storing Strings, Basic String Operations, Accessing Characters in String by Index Number, String Slicing and Joining, String Methods, Formatting Strings.

Lists: list operations, list slices, list methods, list loop, mutability, aliasing, cloning lists, list parameters; **Tuples:** tuple assignment, tuple as a return value; **Dictionaries:** operations and methods; advanced list processing - list comprehension.

UNIT-III

Files and Exception: Text files, reading and writing files, format operator; command line arguments, errors and exceptions, handling exceptions, modules, packages; Illustrative programs: word count, copy file.

Strings: Basic String Operations, String Slicing, Testing, Searching, and Manipulating Strings

Dictionaries and Sets: Dictionaries, Sets, Serializing Objects.

UNIT-IV

Object-Oriented Programming: Classes and Objects, Creating Classes in Python, Creating Objects in Python, The Constructor Method, Classes with Multiple Objects, Class Attributes versus Data Attributes, Encapsulation, Inheritance the Polymorphism.

Functional Programming: Lambda. Iterators, Generators, List Comprehensions.

UNIT-V

GUI Programming: Graphical User Interfaces, Using the Tkinter Module, Display text with Label Widgets, Organizing Widgets with Frames, Button Widgets and Info Dialog Boxes, Getting Input with Entry Widget, Using Labels as Output Fields, Radio Buttons, Check Buttons.

Suggested Readings:

1. Richard L. Halterman, *“Learning To Program With Python”*, Copyright fi 2011.
2. Dr CharlesR, *“Python for Everybody, Exploring Data Using Python 3”*, Severance. 2016.
3. Gowrishankar S., Veena A, *“Introduction to Python Programming”*, CRC Press, Taylor & Francis Group, 2019.
4. Allen B. Downey, *“Think Python: How to Think Like a Computer Scientist”*, 2nd edition, Updated for Python 3, Shroff/O’Reilly Publishers, 2016
(<http://greenteapress.com/wp/think-python/>)

EE 3151

DRIVES LABORATORY - I

Instruction: 2 hours per week

CIE: 50 marks

Credits: 1

Course Objectives

- To Analyze and design rectifier fed DC motors.
- To Analyze and design single phase and three-phase inverters with and without PWM.
- To Analyze and design Buck boost converter.

Course Outcomes

After completion of this course, the students shall be able to:

1. Simulate steady state and dynamic response of rectifier fed DC motors.
2. Simulate steady state and dynamic response of single phase and three-phase inverters with and without PWM.
3. Simulate steady state and dynamic response of Buck boost converter.
4. Write MATLAB programming for single-phase and three-phase inverters.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	3	3	3	-	2
CO2	3	3	3	3	-	2
CO3	3	3	3	3	-	2
CO4	3	3	3	3	-	2
CO5	3	3	3	3	-	2

List of Experiments

1. Simulation of Single phase Fully controlled Rectifier fed SEDC Motor
2. Simulation of Single phase Fully controlled Rectifier fed DC Series Motor
3. Simulation of Square wave, Single pulse Modulation for Single phase inverter.
4. Simulation of Six step operation of Three phase Inverter
 - (i) 180° Conduction mode
 - (ii) 120° Conduction mode
5. Simulation of Unipolar and Bipolar PWM for Single phase inverter.

6. Simulation of Sinusoidal PWM for three phase Inverter
7. Simulation of Buck Boost converter
8. 180° and 120° Conduction modes of Three phase Inverter using MATLAB programming.
9. Single pulse Modulation for Single phase inverter using MATLAB programming.
10. Multiple Pulse Modulations for Single phase inverter using MATLAB programming.

EE 3161

SEMINAR – I

Instruction	: 2 hours per week
Duration of SEE	: --
SEE	: --
CIE	: 50 Marks
Credits	: 1

Course Objectives

- Identify appropriate topic of relevance.
- Update literature on technical articles of selected topic and develop comprehension.
- Prepare a technical report.
- Deliver presentation on specified technical topic.

Course Outcomes

After the completion of this course, the students shall be able to:

1. Develop the habit of referring the journals for literature review.
2. Understand the gist of the research paper.
3. Identify the potential for further scope.
4. Present the work in an efficient manner.
5. Write the documentation in standard format.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	2	3	3	-	-	2
CO2	2	3	3	-	-	2
CO3	2	3	3	-	-	2
CO4	2	3	3	-	-	2
CO5	2	3	3	-	-	2

Seminar topics may be chosen by the students with advice from the faculty members and the student shall read further relevant articles in the domain.

The seminar must be clearly structured and the power point presentation shall include following aspects:

1. Introduction to the field
2. Literature survey
3. Consolidation of available information
4. Summary and Conclusions
5. References

Each student is required to:

1. Deliver the seminar for a maximum duration of 30 minutes, where the presentation should be for 20 minutes in PowerPoint, followed by Question and Answers session for 10 minutes.
2. Submit the detailed report of the seminar in spiral bound in a précised format as suggested by the Department.

Guidelines for awarding marks		
S. No.	Description	Max. Marks
1	Contents and relevance, Report in a prescribed format	10
2	Presentation skills	05
3	Preparation of PPT slides	05
4	Questions and answers	05
	TOTAL	25

Note:

1. The seminar presentation should be a gist of at least five research papers from **Peer-reviewed** or **UGC recognised** journals.
2. **The seminar report should be in the following order:** Background of work, literature review, techniques used, prospective deliverables, discussion on results, conclusions, critical appraisal and reference.
3. At least two faculty members will be associated with the seminar presentation to evaluate and award marks.
4. Attendance of all the students for weekly seminar presentations is compulsory. If the student fails to secure minimum attendance as per O.U. rules, the marks awarded in the seminar presentation shall remain void.

EE3104

DYNAMICS OF ELECTRIC MACHINES

Instruction: 3 periods per week
CIE: 40 marks
Credits: 3

Duration of SEE: 3 hours
SEE: 60 marks

- To analyze the dynamic and transient performance of DC generators for sudden field excitation, sudden short circuit of armature terminals and short circuit of field terminals.
- To analyze the dynamic and transient performance of DC motors for sudden application of voltage and load.
- To understand the harmonic and inrush current phenomenon in transformers.
- To understand the induction machine dynamics during normal operation and unbalanced supply voltage.
- To study the synchronous machine dynamics for motor and generator operation.

Course Outcomes

After the completion of this course, students will be able to:

1. To model and design the machines keeping in view of the sudden changes or disturbances.
2. To develop the controllers for DC machines, AC Machines when subjected to sudden changes.
3. To apply the qualitative and analytical approaches for overcurrent transients in transformers.
4. To analyze the various operating conditions of induction machines.
5. To apply the different braking methods for synchronous machine.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	-	2
CO2	3	-	3	-	-	2
CO3	3	-	3	-	-	2
CO4	3	-	3	-	2	2
CO5	3	-	3	-	2	2

UNIT I

Dynamics of Separately Excited DC Generator: Steady state analysis, Transient analysis-Sudden step field excitation at no-load and load-Sudden short circuit of armature terminals-Sudden short circuit of field terminals, Generator operation with displaced brushes.

UNIT II

Dynamics of DC Motors: Separately Excited DC Motor–Steady state analysis, Transient analysis– Sudden application of voltage and load torque–Sudden application of inertia load, Transfer function– Dynamic behaviour. DC Series Motor: Steady state analysis– Linearization techniques for small perturbations.

UNIT III

Transformer Transients: Excitation phenomena–Harmonics in single –phase transformers, Over current transients–Qualitative and Analytical approaches. Estimation of inrush current, External and Internal over voltages –Transformer equivalent circuit with over voltages-Initial voltage distribution for solidly grounded neutral and isolated neutral.

UNIT IV

Induction Machine Dynamics: Dynamics during starting and braking–Accelerating time– Dynamics during normal operation, Operation on unbalanced supply voltages– Equivalent circuit, Operation on Single phasing– Equivalent circuit.

UNIT V

Synchronous Machine Dynamics: Electro-mechanical equation- Motor operation- Generator operation- Linearized analysis, Cyclic variations of shaft torque, Electric braking-Plugging and Dynamic braking.

References

1. Bhimbra P.S. *Generalized Theory of Electrical Machines*, Khanna Publishers, 2002.
2. Nagrath I.J. & Kothari D.P, *Electric Machines*, Tata McGraw Hill Publishers, 2004.

EE3105

STATIC CONTROL OF A.C. DRIVES

Instruction: 3 periods per week
CIE: 40 marks
Credits: 3

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- To understand the static control of Induction Motor Drives.
- To understand the performance of Inverter fed Induction Motor Drives.
- To understand the control of Induction Motor Drives using vector control.
- To understand the control of Synchronous Motor Drives using VSI, CSI and cycloconverter.
- To understand the control of Special Machines such as BLDC, PMSM, Stepper Motor and SRM

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	-	2
CO2	3	-	3	-	-	2
CO3	3	-	3	-	-	2
CO4	3	-	3	-	2	2
CO5	3	-	3	-	2	2

Course Outcomes
After the completion of this course, students

will be able to:

1. Understand slip power recovery schemes for static control of Induction Motor Drives.
2. Analyze VSI and CSI to achieve efficient performance of Induction motor drive using various waveforms.
3. Implement high performance Induction Motor Drives using principle of vector control.
4. Apply the modes of variable frequency control for Synchronous Motor Drives employing Inverters.
5. Analyze the control requirements and performance of Special Electrical Machines.

UNIT I

Static Control of Induction Motor Drives: Stator Voltage Control, Static rotor resistance control, Slip power recovery schemes – Static Kramer drive, Static Scherbius drive, Closed loop control of the above schemes.

UNIT II

Inverter Fed Induction Motor Drives: Voltage Source Inverter and Current Source Inverter fed Induction motors, Analysis of Stepped waveform and PWM waveform, Harmonic equivalent circuit and motor performance.

UNIT III

Vector Control: Principle of vector control, Direct vector control –Flux & Torque processor using terminal voltages and Induced emf, Principle of Space vector modulation, Indirect vector control – Flow chart and implementation.

UNIT IV

Static Control of Synchronous Drives:Self-control and Separate control of synchronous motor fed from VSI, Cyclo-converter fed self-control of synchronous motor, CSI fed synchronous motor drive, LCI self-controlled synchronous motor.

UNIT V

Special Machines: Brushless D.C Motor – Unipolar and Bipolar Brushless D.C motors, Applications, Stepper Motors – Variable reluctance and Permanent magnet stepper motors – Characteristics & Drive circuits, Switched reluctance motor.

References

1. R.Krishrian, *Electric Motor Drives*, Prentice Hall of India Pvt. Ltd., New Delhi, 2002.
2. G.K.Dubey, *Fundamentals of Electrical Drives*, Narosa Publishing House, New Delhi, 1999.
3. W.Shepard, LN.Hulley and D.T.W.Liang, *Power Electronics and Motor Control*, Cambridge University Press, 1995.
4. B.K.Bose, *Modern Power Electronics and A.C.Drives*, Prentice Hall, 2002.

EE 3106

POWER ELECTRONIC CONVERTERS

Instruction: 3 periods per week

CIE: 40 marks

Credits: 3

Duration of SEE: 3 hours

SEE: 60 marks

Course Objectives

- To get insight into power semiconductor switching devices, switching characteristics and the concept of power electronic converters.
- To prepare the students for acquiring the knowledge of different types of power semiconductor devices, rectifier circuits, switched mode converters and pulse width modulated inverters.
- To develop the ability to comprehend, analyze, design various types of switched mode DC-DC converters and pulse width modulated inverters used in variable speed drives

Course Outcomes

After the completion of this course, students will be able to:

1. Select an appropriate power semiconductor device and design a power converter for the required application.
2. Select and design power electronic converters for broad range of energy conversion applications.
3. Design the control circuit and the power circuit for a given power converter.
4. Use power electronic simulation tools for analyzing and designing power electronic converter circuits.
5. Experimentally evaluate the performance of power electronic conversion systems for different types of electrical applications.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	3	2	2
CO2	3	-	3	3	2	2
CO3	3	-	3	3	2	2
CO4	3	-	3	3	2	2
CO5	3	-	3	3	2	2

UNIT I

Power Switching Devices – Characteristics: Classification of switches-ideal switches and real switches; Practical power switching devices-uncontrolled switches, semi controlled switches and fully controlled switches; Power diodes, Thyristors, Power transistors - Power BJT, MOSFETS, IGBT static and dynamic characteristics and their applications; Firing circuit for thyristor; Voltage and current commutation of a thyristor; Gate drive circuits for MOSFET and IGBT.

UNIT II

Rectifiers: Line commutated rectifiers-Diode and Thyristor Rectifiers-Single-phase half-wave, full-wave and semi controlled rectifiers with R-load and highly inductive load; Three-phase half-wave, full-wave and semi controlled bridge thyristor rectifier with R-load and highly inductive load; Input current wave shape and power factor.

PWM rectifiers- Single-phase PWM rectifiers, bridge-connected PWM rectifier: voltage-doubler PWM rectifier, three-phase voltage source PWM rectifier.

UNIT III

DC-DC Converters: Elementary chopper with an active switch and diode, concepts of duty ratio and average voltage across an inductor and average current through a capacitor operating in periodic steady state, power circuit and operation of buck, boost, buck-boost, flyback, forward, push-pull, half-bridge and full-bridge converters in continuous conduction mode, duty ratio control of output voltage.

AC-AC Converter: Power circuit and operation of single-phase AC Voltage Controller with R & RL Load. Basic concepts of Cycloconverter and Matrix converter.

UNIT IV

Single-phase inverter: Power circuit and operation of single-phase voltage source inverter in square wave mode, sinusoidal pulse width modulation (unipolar and bi-polar), relation between modulation index and output voltage. Calculation of performance parameters of inverter.

UNIT V

Three-phase inverter: Power circuit and operation of three-phase voltage source inverter in 180° and 120° modes, Uni-polar sinusoidal pulse width modulation, relation between modulation index and output voltage and Space vector modulation technique; Elementary operation of CSI, comparison of voltage source inverter and current source inverter.

References

1. N. Mohan and T. M. Undeland, "Power Electronics: Converters, Applications and Design", John Wiley & Sons, 2007.
2. R. W. Erickson and D. Maksimovic, "Fundamentals of Power Electronics", Springer Science & Business Media, 2007.
3. L. Umanand, "Power Electronics: Essentials and Applications", Wiley India, 2009.
4. Dr. P.S. Bhimbra, "Power Electronics", Khanna Publishers, 2009.
5. M. H. Rashid, "*Power electronics: circuits, devices, and applications*", Pearson Education India, 2017.

EE3141

MODERN CONTROL THEORY

Instruction: 3 periods per week
CIE: 40 marks
Credits: 3

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- To provide the fundamentals required to model a control system in state space and check its controllability and observability.
- To educate the students about non-linear systems behavior and the methods to determine their stability.
- To make then students thorough with Lyapunov stability analysis.
- To familiarize the students with the concept of optimal control and how to determine optimum for functional using calculus of variations.
- To introduce the concept of Adaptive control and explain how to design a Model Reference Adaptive System.

Course Outcomes

After the completion of this course, students shall be able to:

1. Model any control system in state space.
2. Understand the behavior of nonlinear system and methods of determining stability.
3. Determine stability of nonlinear system using Liapunov method.
4. Formulate optimal control problem and determine optimum of functionals.
5. Understand and design adaptive control problem.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	-	2
CO2	3	-	3	-	-	2
CO3	3	-	3	-	-	2
CO4	3	-	3	-	-	2
CO5	3	-	3	-	-	2

Syllabus Contents

UNIT I

Review of state variable representation of systems - Controllability and Observability –Model control of single input – single output systems (SISO), Controllable and Observable companion forms – Effect of state feedback on Controllability and Observability, Pole placement by state feedback.

UNIT II

Classification of Non-linearities: Phenomenon exhibited by the nonlinearities – Limit cycles – Jump resonance, Sub-harmonic oscillations – Phase plane analysis – Singular points – Construction of phase plane trajectories – Isocline method – Delta method – Measurement of time on phase plane trajectories.

UNIT III

Concept and definition of stability - Lyapunov stability - Lyapunov's first and second methods - Stability of linear time invariant systems by Lyapunov's second method - Generation of Lyapunov functions- Variable gradient method - Krasooviski's method.

UNIT IV

Formulation of optimal control problems - Calculus of variations – Fundamental concepts – Functionals – Variation of functionals – Fundamental theorem of calculus of variations - Boundary conditions – Constrained minimization – Dynamic programming – Hamilton Principle of optimality, Jacobi Bellman equation – Potryagins minimum principle.

UNIT V

Introduction to adaptive control, types of adaptive control systems. Design of model reference adaptive control systems using M/T rule and Lyapunov stability theorem.

References

1. I.J Nagarath ,M.Gopal *Control Systems Engineering*, fifth edition , New Age International Publishers, 1984 Wiley Eastern Ltd.
2. Ogata K, *Modern Control Engineering*, Prentice Hall, 1997. Donald E Kirk, optimal control theoryAn introduction
3. Karl J AstromBjronwihenmark, *Adaptive control* second edition – Pearson education.

EE 3142

SMART GRID TECHNOLOGIES

Instruction: 3 periods per week
CIE: 40 marks
Credits: 3

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- To group various aspects of the smart grid,
- To defend smart grid design to meet the needs of a utility
- To select issues and challenges that remain to be solved
- To analyze basics of electricity, electricity generation, economics of supply and demand, and the various aspects of electricity market operations in both regulated and deregulated environment.

Course Outcomes

After the completion of this course, students will be able to:

- Analyze the structure of an electricity market in either regulated or deregulated market conditions.
- know the advantages of DC distribution and developing technologies in distribution
- Discriminate the trade-off between economics and reliability of an electric power system.
- Differentiate various investment options (e.g. generation capacities, transmission, renewable, demand-side resources, etc) in electricity markets.
- Analyze the development of smart and intelligent domestic systems.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	2	2	2
CO2	3	-	3	2	2	2
CO3	3	-	3	2	2	2
CO4	3	-	3	2	2	2
CO5	3	-	3	2	2	2

UNIT-I:

Introduction to smart grid - Electricity network - Local energy networks- Electric transportation - Low carbon central generation - Attributes of the smart grid - Alternate views of a smart grid. Smart grid to evolve a perfect power system: Introduction- Overview of the perfect power system configurations- Device level power system- Building integrated power systems- Distributed power systems- Fully integrated power system-Nodes of innovation.

UNIT-II

DC Distribution And Smart Grid AC Vs DC sources-Benefits of and drives of DC power delivery systems - Powering equipment and appliances with DC-Data centers and information technology loads - Future neighborhood-Potential future work and research. Intelligrid Architecture For The Smartgrid: Introduction- Launching intelli-grid –Intelligrid today - Smart grid vision based on the intell-igrid architecture-Barriers and enabling technologies.

UNIT-III:

Dynamic Energy Systems Concept: Smart energy efficient end use devices-Smart distributed energy resources - Advanced whole building control systems- Integrated communications architecture - Energy management-Role of technology in demand response- Current limitations to dynamic energy management-Distributed energy resources. Overview of a dynamic energy management-Key characteristics of smart devices- Key characteristics of advanced whole building control systems-Key characteristics of dynamic energy management system.

UNIT-IV: Energy Port as Part of The Smart Grid: Concept of energy - Port, generic features of the energy port. Policies and Programs to Encourage End – Use Energy Efficiency: Policies and programs in action - multinational - national-state-city and corporate levels. Market Implementation: Framework-factors influencing customer acceptance and response - program planning - monitoring and evaluation.

UNIT-V: Efficient Electric End–Use Technology Alternatives Existing technologies – lighting - Space conditioning - Indoor air quality - Domestic water heating - hyper efficient appliances - Ductless residential heat pumps and air conditioners - Variable refrigerant flow air conditioning-Heat pump water heating - Hyper efficient residential appliances - Data center energy efficiency- LED street and area lighting - Industrial motors and drives - Equipment retrofit and replacement - Process heating - Cogeneration, Thermal energy storage - Industrial energy management programs - Manufacturing process- Electro-technologies, Residential, Commercial and industrial sectors.

TEXT BOOKS: 1. Clark W Gellings, “The Smart Grid, Enabling Energy Efficiency and Demand Side Response”- CRC Press, 2009. 2. Jean Claude Sabonnadière, NouredineHadjsaïd, “Smart Grids”, Wiley-ISTE, IEEE Press, May 2012

References

1. Janaka Ekanayake, KithsiriLiyanage, Jianzhong.Wu, Akihiko Yokoyama, Nick Jenkins, “Smart Grid: Technology and Applications”- Wiley, 2012.
2. James Momoh, “Smart Grid: Fundamentals of Design and Analysis” - Wiley, IEEE Press, 2012.

EE 3143

GRID INTEGRATION OF DISTRIBUTED GENERATION

Instruction: 3 periods per week

CIE: 40 marks

Credits: 3

Duration of SEE: 3 hours

SEE: 60 marks

Objectives:

- To study about various types of power generation resources to be connected in distributed generation system.
- To know the architecture of smart grid with integrated distribution generation with various plants.
- To get the knowledge on smart grid and how will gain the efficient power to the distributed end.
- To get the knowledge of Smart grid to evolve a perfect power system

Course Outcomes:

After completion of the course the student will able to:

- Understand about the distribution generation system connected with various power generation plants.
- Gain the knowledge on smart grid by various techniques for better efficiency in transmitting the power.
- Know about the integration of distribution generation with various plants to the smart grid.
- Overview of the perfect power system configurations.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	3	3	-
CO2	3	-	3	3	3	-
CO3	3	-	3	3	3	-
CO4	3	-	3	3	3	-

UNIT- I

Introduction to Distributed Generation: The development of the electrical power system - Value of distributed generation and network pricing – Reasons for distributed generation - The future development of distributed generation - Distributed generation and the distribution system - Technical impacts of generation on the distribution system - Economic impact of distributed generation on the distribution system - Impact of distributed generation on the transmission system - Impact of distributed generation on central generation.

UNIT-II

Distributed generation plant Combined heat and power plants - Renewable energy generation - Small-scale hydro generation - Wind power plants - Offshore wind energy - Solar photovoltaic generation

UNIT-III

Distributed generators and their connection to the system - Distributed generators - Synchronous generators - Induction generators - Doubly fed induction generator - Full power converter (FPC) connected generators - System studies - Load flow studies in a simple radial system - Load flow studies in meshed systems - Symmetrical fault studies - Unbalanced (asymmetrical) fault studies - Case studies - Steady-state voltages under peak and minimum loading - Electromagnetic transient studies.

UNIT-IV

DC Distribution - AC vs DC sources-Benefits of and drives of DC power delivery systems-Powering equipment and appliances with DC-Data centers and information technology loads-Future neighborhood - Potential future work and research.

UNIT-V

Smart Grid to Evolve a Perfect Power System - Electricity Network-Local energy networks- Electric transportation- Low carbon central generation-Attributes of the smart grid- Alternate views of a smart grid. Overview of the perfect power system configurations- Device level power system- Building integrated power systems- Distributed power systems- Fully integrated power system-Nodes of innovation.

References

1. "Distributed Generation" by N.Jenkins, J.B. Ekanayake & G. Strbac
2. Clark W Gellings, "The Smart Grid, Enabling Energy Efficiency and Demand Side Response"- CRC Press, 2009.
3. Janaka Ekanayake, Kithsiri Liyanage,Jianzhong.Wu, Akihik Yokoyama, Nick Jenkins, "Smart Grid: Technology and Applications"- Wiley, 2012.
4. IEEE 1547. IEEE Standard for Interconnecting Distributed Resources with Electric Power Systems; 2003.
5. James Momoh, "Smart Grid : Fundamentals of Design and Analysis"- Wiley, IEEE Press, 2012.
6. Horlock J.H. Cogeneration: Combined Heat and Power Thermodynamics and Economics. Oxford: Perga

EE3124

HYBRID ELECTRICAL VEHICLES

Instruction: 3 periods per week

CIE: 40 marks

Credits: 3

Duration of SEE: 3 hours

SEE: 60 marks

Course Objectives

- To understand the basics of electric and hybrid electric vehicles and their working
- To understand the basics of batteries and their role for electric/hybrid vehicle applications
- To obtain the knowledge of various types of electric/hybrid vehicles
- To understand the real time challenges in the implementation of this technology

Course Outcomes

After the completion of this course, the students shall be able to:

1. Understand basics of electric and hybrid electric vehicles both conceptually and mathematically so that clear understanding from basics physics is achieved.
2. Have the knowledge of battery behavior for electric vehicle application.
3. Understand different types of Electric/Hybrid vehicles technologies available and their applications.
4. Analyze challenges in implementing electric/hybrid vehicle technology by looking into various charging topologies and their impact on distribution systems.
5. Analyze various electric drives suitable for hybrid electric vehicles.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	-	2
CO2	3	-	3	-	-	2
CO3	3	-	3	2	-	2
CO4	3	-	3	2	-	2
CO5	3	-	3	2	-	2

UNIT I

Introduction to Electric Vehicles: Sustainable Transportation - EV System – EV - Advantages - Vehicle Mechanics - Performance of EVs - Electric Vehicle drivetrain - EV Transmission Configurations and components-Tractive Effort in Normal Driving - Energy Consumption - EV Market - Types of Electric Vehicle in Use Today – Electric Vehicles for the Future.

UNIT II

Electric Vehicle Modelling - Consideration of Rolling Resistance – Transmission Efficiency - Consideration of Vehicle Mass - Tractive Effort - Modelling Vehicle Acceleration - Modelling Electric Vehicle Range - Aerodynamic Considerations - Ideal Gearbox Steady State Model - EV Motor Sizing - General Issues in Design.

UNIT III

Introduction to electric vehicle batteries - electric vehicle battery efficiency – electric vehicle battery capacity - electric vehicle battery charging - electric vehicle battery fast charging - electric vehicle battery discharging - electric vehicle battery performance – testing.

UNIT IV

Hybrid Electric Vehicles - HEV Fundamentals - Architectures of HEVs- Interdisciplinary Nature of HEVs - State of the Art of HEVs - Advantages and Disadvantages - Challenges and Key Technology of HEVs - Concept of Hybridization of the Automobile-Plug-in Hybrid Electric Vehicles - Design and Control Principles of Plug-In Hybrid Electric Vehicles - Fuel Cell Hybrid Electric Drive Train Design - HEV Applications for Military Vehicles.

UNIT V

Advanced Topics - Battery Charger Topologies, Charging Power Levels, and Infrastructure for Plug-In Electric and Hybrid Vehicles - The Impact of Plug-in Hybrid Electric Vehicles on Distribution Networks – Sizing Ultra capacitors for Hybrid Electric Vehicles.

References

1. Modern Electric, Hybrid Electric and Fuel Cell Vehicles –Fundamentals, Theory and Design – Mehrdad Ehsani, UiminGao and Ali Emadi - Second Edition - CRC Press, 2010.
2. Electric Vehicle Technology Explained - James Larminie, John Lowry – John Wiley & Sons Ltd, - 2003.
3. Electric Vehicle Battery Systems – Sandeep Dhameja – Newnes - 2002.
4. Hybrid electric Vehicles Principles and applications with practical perspectives Chris Mi, Dearborn - M. AbulMasrur, David WenzhongGao - A John Wiley & Sons, Ltd., - 2011.
5. Electric & Hybrid Vehicles – Design Fundamentals-IqbalHussain, SecondEdition, CRC Press, 2011.
6. Research Papers:
 - a. The Impact of Plug-in Hybrid Electric Vehicles on Distribution Networks: a Review and Outlook - Robert C. Green II, Lingfeng Wang andMansoorAlam - 2010 IEEE.
 - b. Sizing Ultracapacitors For Hybrid Electric Vehicles - H. Douglas P Pillay 2005 IEEE.
 - c. Review of Battery Charger Topologies, Charging Power Levels, and Infrastructure for Plug-In Electric and Hybrid Vehicles - Murat Yilmaz, and Philip T. Krein, - IEEE transactions on power electronics, vol. 28, no. 5, may 2013.

EE 3152

DIGITAL CIRCUITS AND LOGIC DESIGN

Instruction: 3 periods per week
CIE: 40 marks
Credits: 3

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- To understand the concepts of contact networks and combinational circuit design.
- To distinguish between melay model and moore model and analyze the sequential circuits.
- To simplify the sequential circuits.
- To assess the asynchronous sequential circuits.
- To analyze races, cycles, hazards and test sequential circuits.

Course Outcomes

The students will

1. Create the contact networks and identify symmetric functions and acquire the knowledge of combinational circuit design with PLA, PROM and PAL.
2. Design the completely specified and incompletely specified synchronous sequential circuits.
3. Apply the simplification techniques for state reduction in completely specified and incompletely specified synchronous sequential circuits.
4. Design the pulse mode and fundamental mode asynchronous sequential circuits.
5. Design the circuits to avoid race conditions and test the sequential logic circuits using transfer tree and homing tree.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	2	2	1
CO2	3	-	3	2	2	1
CO3	3	-	3	2	-	-
CO4	3	-	3	2	2	1
CO5	3	-	3	2	2	1

UNIT I

Contact networks: Relay contacts and their symbols- Analysis of series-parallel networks, Analysis of non-series-parallel networks, Synthesis of contact networks-Symmetric networks –Synthesis of symmetric networks-Identification of symmetric functions.

Combinational circuit design with Programmable Logic Devices: Realizing logic functions with Programmable Logic Array, Programmable Read-Only Memory and Programmable Array Logic.

UNIT II

Synchronous sequential circuits: Block diagram, Mealy model and Moore model, Flip-Flop input tables, Analysis of synchronous sequential circuit logic diagrams, Synthesis of synchronous sequential circuits, Design of Incompletely specified synchronous sequential circuits.

UNIT III

Simplification of Sequential Circuits: State equivalence, State reduction in completely specified circuits using Inspection, Partitioning and Implication table, State reduction in incompletely specified sequential circuits using Merger diagrams.

UNIT IV

Asynchronous sequential circuits: Types of Asynchronous Circuits, Pulse-mode circuit model and Fundamental-mode circuit model, Analysis of Pulse-mode asynchronous circuits, Synthesis of pulse-mode asynchronous circuits, Analysis of fundamental-mode circuits and Synthesis of fundamental-mode circuits.

UNIT V

Introduction to Races, Cycles and Hazards: Races- critical race and non-critical race, Cycle, Hazards- static hazard, dynamic hazard and essential hazard, realization of circuits with races, Avoidance of race conditions, Race-free state assignments, critical race-free realization.

Sequential logic circuit testing: test sequence, initialization sequence, observation sequence, transfer sequence, homing sequence, pre-set homing sequence, Implementation of transfer tree and homing tree.

References

1. Z.Kohavi, *Switching and Finite Automata Theory*, Tata McGraw Hill, 48th Reprint 2010.
2. Victor P.Nelson, H.Troy Nagle, Bill D Caroll, J.David Irwin, *Digital Logic Circuit Analysis and Design*, Prentice Hall International, 1996.

EE 3351

BATTERY MANAGEMENT SYSTEMS AND CHARGING STATIONS

Instruction: 3 periods per week

CIE: 40 marks

Credits: 3

Duration of SEE: 3 hours

SEE: 60 marks

Course objectives:

- Able to understand the working of different batteries for EV applications
- Able to know the fundamentals of battery charging methods and their advantages
- Able to know the different kinds of equipment in charging station
- Able to know the requirements of battery management.
- Able to know method of modelling batteries and their simulation studies.

Course Outcomes:

After the completion of the course the student should be able to:

- Describe the construction and operation of different batteries for EV applications Describe charging algorithms of different batteries and balancing methods of battery packs
- Describe the different kinds of infrastructure needed in the charging stations
- Describe the requirements of battery management and their maintenance.
- Obtain the modelling of batteries and develop their simulation models.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	3		2
CO2	3	-	3	3		2
CO3	3	-	3	3		2
CO4	3	-	3	3		2

Unit - I:

EV Batteries Cells & Batteries, Nominal voltage and capacity, C rate, Energy and power, Cells connected in series, Cells connected in parallel. Lead Acid Batteries: Lead acid battery basics, special characteristics of lead acid batteries, battery life and maintenance, Li-ion batteries. Nickel-based Batteries: Nickel cadmium, Nickel metal hydride batteries. Sodium-Based Batteries: Introduction, sodium sulphur batteries, sodium metal chloride (Zebra) batteries. Lithium Batteries: Introduction, the lithium polymer battery, lithium ion battery.

Unit - II:

Battery charging strategies Charging algorithms for a single battery: Basic terms for charging performance evaluation and characterization, CC charging for NiCd/NiMH batteries, CV charging for

lead acid batteries, CC/CV charging for lead acid and Li-ion batteries, MSCC charging for lead acid, NiMH and Li-ion batteries, TSCC/CV charging for Li-ion batteries, CVCC/CV charging for Li-ion batteries, Pulse charging for lead acid, NiCd/NiMH and Li-ion batteries, Charging termination techniques, Comparisons of charging algorithms and new development; Balancing methods for battery pack charging: Battery sorting Overcharge for balancing, Passive balancing, Active balancing.

Unit -III:

Charging Infrastructure Domestic Charging Infrastructure, Public charging Infrastructure, Normal Charging Station, Occasional Charging Station, Fast Charging Station, Battery Swapping Station, Move-and-charge zone.

Unit - IV:

Battery-Management-System Requirements Battery-pack topology, BMS design requirements, Voltage sense, Temperature sense, Current sense, Contactor control, Isolation sense, Thermal control, Protection, Charger control, Communication via CAN bus, Log book, SOC estimation, Energy estimation, Power estimation, Diagnostics .

Unit - V:

Battery Modelling General approach to modelling batteries, simulation model of rechargeable Li-ion battery, simulation model of a rechargeable NiCd battery, Parameterization of NiCd battery model, Simulation examples.

References

1. *Electric Vehicles Technology Explained* by James Larminie Oxford Brookes University, Oxford, UK John Lowry Acenti Designs Ltd., Uk.
3. *Energy Systems for Electric and Hybrid Vehicles* by K.T. Chau, IET Publications, First edition, 2016.
4. *Modern Electric Vehicles Technology* by C.C.Chan, K.T Chau, Oxford University Press Inc., New york , 2001.
5. *Battery Management Systems Vol. – II Equivalent Circuits and Methods*, by Gregory L.Plett, Artech House publisher, First edition 2016.
6. *3. Battery Management Systems: design by Modelling* by Henk Jan Bergveld, Wanda S. Kruijt, Springer Science & Business Media, 2002.

OE901EE

WASTE TO ENERGY

Instruction: 3 periods per week

CIE: 40 marks

Credits: 3

Duration of SEE: 3 hours

SEE: 60 marks

Course Objectives

- To know the various forms of waste
- To understand different gasification systems.
- To understand the processes of Biomass Pyrolysis.
- To learn the technique of Biomass Combustion.
- To learn the technique of Biomass technologies

Course Outcomes

After the completion of this course, the students shall be able to:

- Understand the concept of conservation of waste
- Identify the different forms of wastage
- Chose the best way for conservation to produce energy from waste
- Explore the ways and means of combustion of biomass
- Develop a healthy environment for the mankind

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	2	3	1
CO2	3	-	3	2	3	1
CO3	3	-	3	2	3	1
CO4	3	-	3	2	3	1
CO5	3	-	3	2	3	1

UNIT I

Introduction to Energy from Waste: Classification of waste as fuel – Agro based, Forest residue, Industrial waste - MSW – Conversion devices – Incinerators, gasifiers, digestors

UNIT II

Biomass Pyrolysis: Pyrolysis – Types, slow fast – Manufacture of charcoal – Methods - Yields and application – Manufacture of pyrolytic oils and gases, yields and applications.

UNIT III

Biomass Gasification: Gasifiers – Fixed bed system – Downdraft and updraft gasifiers – Fluidized bed gasifiers – Design, construction and operation – Gasifier burner arrangement for thermal heating – Gasifier engine arrangement and electrical power – Equilibrium and kinetic

consideration in gasifier operation.

UNIT IV

Biomass Combustion: Biomass stoves – Improved chullahs, types, some exotic designs, Fixed bed combustors, Types, inclined grate combustors, Fluidized bed combustors, Design, construction and operation - Operation of all the above biomass combustors.

UNIT V

Biogas: Properties of biogas (Calorific value and composition) - Biogas plant technology and status - Bio energy system - Design and constructional features - Biomass resources and their classification - Biomass conversion processes - Thermo chemical conversion - Direct combustion - biomass gasification - pyrolysis and liquefaction - biochemical conversion - anaerobic digestion - Types of biogas Plants – Applications - Alcohol production from biomass - Bio diesel production - Urban waste to energy conversion - Biomass energy programme in India.

References

1. Non Conventional Energy, Desai, Ashok V., Wiley Eastern Ltd., 1990.
2. Biogas Technology - A Practical Hand Book - Khandelwal, K. C. and Mahdi, S. S., Vol. I & II, Tata McGraw Hill Publishing Co. Ltd., 1983.
3. Food, Feed and Fuel from Biomass, Challal, D. S., IBH Publishing Co. Pvt. Ltd., 1991.
4. Biomass Conversion and Technology, C. Y. WereKo-Brobby and E. B. Hagan, John Wiley & Sons, 1996.

OE902EE

POWER PLANT CONTROL AND INSTRUMENTATION

Instruction: 3 periods per week
CIE: 40 marks
Credits: 3

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives:

The course should enable the students to:

- The operation of different types of power plants.
- The basic working principle of instruments for measurement of electrical and non-electrical quantities like Temperature Pressure flow level measurements.
- The instrumentation and protection systems applied in thermal power plant.
- The control techniques employed for the operation of modern power generation plant

Course Outcomes:

After successful completion of the course, students should be able to:

- Explain the different methods of power generation. Along with Piping and Instrumentation diagram of boiler.
- Select various measurements involved in power generation for measuring electrical and non-electrical parameters.
- Identify the different types of analyzers used for scrutinizing boiler steam and water.
- Model different types of controls and control loops in boilers.
- Illustrate the methods of monitoring and control of different parameters like speed, vibration of turbines.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	2	1
CO2	3	-	3	-	2	1
CO3	3	-	3	-	2	1
CO4	3	-	3	-	2	1
CO5	3	-	3	-	2	1

UNIT - I

Overview Of Power Generation Classes: Brief survey of methods of power generation, hydro, thermal, nuclear, solar and wind power, importance of instrumentation in power generation, thermal power plants, block diagram, details of boiler processes, Piping and Instrumentation diagram of boiler, cogeneration.

UNIT - II

Measurements In Power Plants Classes: Electrical measurements, current, voltage, power, frequency, power factor etc., non-electrical parameters, flow of feed water, fuel, air and steam with correction factor for temperature, steam pressure and steam temperature, drum level measurement, radiation detector, smoke density measurement, dust monitor.

UNIT - III

Analyzers In Power Plants Classes: Flue gas oxygen analyzer: Analysis of impurities in feed water and steam, dissolved oxygen analyzer. Chromatography, pH meter, fuel analyzer, pollution monitoring instruments.

UNIT - IV

Control Loops in Boiler Classes: Combustion control, air / fuel ratio control, furnace draft control, drum level control, main steam and reheat steam temperature control, super heater control, air temperature, distributed control system in power plants, interlocks in boiler operation.

UNIT - V

Turbine Monitoring and Control Classes: Speed, vibration, shell temperature monitoring and control, steam pressure control, lubricant oil temperature control, cooling system.

References

1. Sam G. Dukelow, The Control of Boilers, Instrument Society of America, 2nd Edition, 2010.
2. P.K. Nag, „Power Plant Engineering“, Tata McGraw-Hill, 1st Edition, 2001.
3. S.M. Elonka and A.L. Kohal, “Standard Boiler Operations”, Tata McGraw-Hill, 1st Edition, 1994.
4. R K Jain, “Mechanical and Industrial Measurements”, Khanna Publishers, 1st Edition, 1995.
5. E Al Wakil, “Power Plant Engineering”, Tata McGraw-Hill, 1st Edition, 1984.

OE941CS

BUSINESS ANALYTICS

Instruction: 3 periods per week
CIE: 40 marks
Credits: 3

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- To understand the role of business analytics within an organization.
- To analyze data using statistical and data mining techniques and understand relationships between the underlying business processes of an organization.
- To gain an understanding of how managers use business analytics to formulate and solve business problems and to support managerial decision making.
- To become familiar with processes needed to develop, report, and analyze business data.
- To use decision-making tools/Operations research techniques and manage business process using analytical and management tools.

Course Outcomes

After the completion of this course, the students shall be able to:

1. Understand the basic concepts of business analytics.
2. Identify the application of business analytics and use tools to analyze business data.
3. Become familiar with various metrics, measures used in business analytics.
4. Illustrate various descriptive, predictive and prescriptive methods and techniques.
5. Model the business data using various business analytical methods and techniques.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	-	1
CO2	3	-	3	-	-	1
CO3	3	-	3	-	-	1
CO4	3	-	3	-	-	1
CO5	3	-	3	-	-	1

Syllabus Contents

UNIT I

Introduction to Business Analytics: Introduction to Business Analytics, need and science of data driven (DD) decision making, Descriptive, predictive, prescriptive analytics and techniques, Big data analytics, Web and Social media analytics, Machine Learning algorithms, framework for decision making, challenges in DD decision making and future.

UNIT II

Descriptive Analytics: Introduction, data types and scales, types of measurement scales, population and samples, measures of central tendency, percentile, decile and quadrille, measures of variation, measures of shape-skewness, data visualization

UNIT III

Forecasting Techniques: Introduction, time-series data and components, forecasting accuracy, moving average method, single exponential smoothing, Holt's method, Holt-Winter model, Croston's forecasting method, regression model for forecasting, Auto regression models, autoregressive moving process, ARIMA, Theil's coefficient

UNIT IV

Decision Trees: CHAID, Classification and Regression tree, splitting criteria, Ensemble and method and random forest. **Clustering:** Distance and similarity measures used in clustering, Clustering algorithms, K-Means and Hierarchical algorithms, **Prescriptive Analytics** - Linear Programming (LP) and LP model building.

UNIT V

Six Sigma: Introduction, introduction, origin, 3-Sigma Vs Six-Sigma process, cost of poor quality, sigma score, industry applications, six sigma measures, DPMO, yield, sigma score, DMAIC methodology, Six Sigma toolbox

References

1. U Dinesh Kumar, "Data Analytics", Wiley Publications, 1st Edition, 2017.
2. Marc J. Schniederjans, Dara G. Schniederjans, Christopher M. Starkey, "Business analytics Principles, Concepts, and Applications with SAS", Associate Publishers, 2015.
3. S. Christian Albright, Wayne L. Winston, "Business Analytics - Data Analysis and Decision Making", 5th Edition, Cengage, 2015.

Web Resources

1. <https://onlinecourses.nptel.ac.in/noc18-mg11/preview>
2. <https://nptel.ac.in/courses/110105089/>

OE942ME

INDUSTRIAL SAFETY

Instruction: 3 periods per week

CIE: 40 marks

Credits: 3

Duration of SEE: 3 hours

SEE: 60 marks

Course Objectives

- To understand industrial safety and remember features of factory act 1948.
- Analyze maintenance tools, corrosion preventive measures and fault causes.
- Assess the importance of periodic inspections and maintenance.

Course Outcomes

After the completion of this course, the students shall be able to:

1. Understand the necessity of industrial safety and remember features of factory act 1948 for health and safety.
2. Analyze the tools used for maintenance.
3. Become thorough of the corrosion preventive measures.
4. Analyze the causes of faults and draw decision trees.
5. Understand importance of periodic maintenance and inspection procedures.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	-	1
CO2	3	-	3	-	-	1
CO3	3	-	3	-	-	1
CO4	3	-	3	-	-	1
CO5	3	-	3	-	-	1

Syllabus Contents

UNIT I

Industrial safety: Accident, causes, types, results and control, mechanical and electrical hazards, types, causes and preventive steps/procedure, describe salient points of factories act 1948 for health and safety, wash rooms, drinking water layouts, light, cleanliness, fire, guarding, pressure vessels, etc, Safety color codes. Fire prevention and firefighting, equipment and methods.

UNIT II

Fundamentals of Maintenance Engineering: Definition and aim of maintenance engineering, Primary and secondary functions and responsibility of maintenance department, Types of maintenance, Types and applications of tools used for maintenance, Maintenance cost & its relation with replacement economy, Service life of equipment.

UNIT III

Wear and Corrosion and their prevention: Wear- types, causes, effects, wear reduction methods, lubricants-types and applications, Lubrication methods, general sketch, working and applications, i. Screw down grease cup, ii. Pressure grease gun, iii. Splash lubrication, iv. Gravity lubrication, v. Wick feed lubrication vi. Side feed lubrication, vii. Ring lubrication, Definition, principle and factors affecting the corrosion. Types of corrosion, corrosion prevention methods.

UNIT IV

Fault tracing:Fault tracing-concept and importance, decision treeconcept, need and applications, sequence of fault-finding activities, show as decision tree, draw decision tree for problems in machine tools, hydraulic, pneumatic,automotive, thermal and electrical equipment's like, i. Any one machine tool, ii. Pump iii. Air compressor, iv. Internal combustion engine, v. Boiler, vi. Electrical motors, Types of faults in machine tools and their general causes.

UNIT V

Periodic and preventive maintenance: Periodic inspection-concept and need, degreasing, cleaning and repairing schemes, overhauling of mechanical components, overhauling of electrical motor, common troubles and remedies of electric motor, repair complexities and its use, definition, need, steps and advantages of preventive maintenance. Steps/procedure for periodic and preventive maintenance of: I. Machine tools, ii. Pumps, iii. Air compressors, iv. Diesel generating (DG) sets, Program and schedule of preventive maintenance of mechanical and electrical equipment, advantages of preventive maintenance. Repair cycle concept and importance

References

1. Maintenance Engineering Handbook, Higgins & Morrow, Da Information Services.
2. Maintenance Engineering, H. P. Garg, S. Chand and Company.
3. Pump-hydraulic Compressors, Audels, Mcgraw Hill Publication.
4. Foundation Engineering Handbook, Winterkorn, Hans, Chapman & Hall London.

OE943ME

OPERATIONS RESEARCH

Instruction: 3 periods per week
CIE: 40 marks
Credits: 3

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- Introduce the concepts of optimization techniques
- Formulation of LPP models
- Basic concepts of Non-linear programming, Dynamic programming, Game theory are introduced.
- Introduce the concepts of optimization techniques
- Formulation of LPP models

Course Outcomes

After the completion of this course, the students shall be able to:

- To apply the dynamic programming to solve problems of discrete and continuous variables.
- apply the concepts of non-linear programming
- Carry out sensitivity analysis
- Model the real world problems and simulate it..
- Apply graph theory, competitive models, and game theory simulations.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	-	1
CO2	3	-	3	-	-	1
CO3	3	-	3	-	-	1
CO4	3	-	3	-	-	1
CO5	3	-	3	-	-	1

Syllabus Contents

UNIT I

Optimization Techniques, Model Formulation, models, General L.R Formulation, Simplex Techniques, Sensitivity Analysis, Inventory Control Models

UNIT II

Formulation of a LPP - Graphical solution revised simplex method - duality theory - dual simplex method - sensitivity analysis - parametric programming

UNIT III:

Nonlinear programming problem - Kuhn-Tucker conditions min cost flow problem - max flow problem - CPM/PERT

UNIT IV

Scheduling and sequencing - single server and multiple server models deterministic inventory models - Probabilistic inventory control models - Geometric Programming.

UNIT V

Competitive Models, Single and Multi-channel Problems, Sequencing Models, Dynamic Programming, Flow in Networks, Elementary Graph Theory, Game Theory Simulation

Suggested Reading:

1. H.A. Taha, Operations Research, An Introduction, PHI, 2008
2. H.M. Wagner, Principles of Operations Research, PHI, Delhi, 1982.
3. J.C. Pant, Introduction to Optimisation: Operations Research, Jain Brothers, Delhi, 2008
4. Hitler Libermann Operations Research: McGraw Hill Pub. 2009
5. Pannerselvam, Operations Research: Prentice Hall of India 2010
6. Harvey M Wagner, Principles of Operations Research: Prentice Hall of India 2010.

OE944CE

COST MANAGEMENT OF ENGINEERING PROJECTS

Instruction: 3 periods per week

CIE: 40 marks

Credits: 3

Duration of SEE: 3 hours

SEE: 60 marks

Course Objectives

- Introduce the concepts of cost management, inventory valuation, decision making
- Fundamentals of cost overruns, project execution and technical activities
- Introduce the concepts of Quantitative techniques for cost management, Linear Programming, PERT/CPM

Course Outcomes

After the completion of this course, the students shall be able to:

1. Understand strategic cost management process, control of cost and decision making based on the cost of the project.
2. Appreciate detailed engineering activities of the project and execution of projects
3. Prepare project report and network diagram
4. Plan Cost Behavior, Profit Planning, Enterprise Resource Planning, Total Quality Management.
5. Apply various quantitative techniques for cost management

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	-	1
CO2	3	-	3	-	-	1
CO3	3	-	3	-	-	1
CO4	3	-	3	-	-	1
CO5	3	-	3	-	-	1

Syllabus Contents

UNIT I

Introduction: Overview of the Strategic Cost Management Process Cost concepts in decision-making; Relevant cost, Differential cost, Incremental cost and Opportunity cost. Objectives of a Costing System; Inventory valuation; Creation of a Database for operational control; Provision of data for Decision-Making.

UNIT II

Project: meaning, Different types, why to manage, cost overruns centres, various stages of project execution: conception to commissioning. Project execution as conglomeration of technical and nontechnical activities. Detailed Engineering activities. Pre project execution main clearances and documents Project team: Role of each member. Importance Project site: Data

required with significance. Project contracts. Types and contents. Project execution Project cost control. Bar charts and Network diagram.

UNIT III

Project commissioning: mechanical and process Cost Behavior and Profit Planning Marginal Costing; Distinction between Marginal Costing and Absorption Costing; Break-even Analysis, Cost-Volume-Profit Analysis. Various decision-making problems. Standard Costing and Variance Analysis.

UNIT IV

Pricing strategies: Pareto Analysis. Target costing, Life Cycle Costing. Costing of service sector. Just-in-time approach, Material Requirement Planning, Enterprise Resource Planning, Total Quality Management and Theory of constraints. Activity-Based Cost Management, Bench Marking; Balanced Score Card and Value-Chain Analysis. Budgetary Control; Flexible Budgets; Performance budgets; Zero-based budgets. Measurement of Divisional profitability pricing decisions including transfer pricing.

UNIT V

Quantitative techniques for cost management, Linear Programming, PERT/CPM, Transportation problems, Assignment problems, Simulation, Learning Curve Theory.

References:

1. Cost Accounting A Managerial Emphasis, Prentice Hall of India, New Delhi
2. Charles T. Horngren and George Foster, Advanced Management Accounting
3. Robert S Kaplan Anthony A. Alkinson, Management & Cost Accounting
4. Ashish K. Bhattacharya, Principles & Practices of Cost Accounting A. H. Wheeler publisher
5. N.D. Vohra, Quantitative Techniques in Management, Tata McGraw Hill Book Co. Ltd.

OE945ME

COMPOSITE MATERIALS

Instruction: 3 periods per week

CIE: 40 marks

Credits: 3

Duration of SEE: 3 hours

SEE: 60 marks

Course Objectives

- Study the concepts of composite construction.
- Learn analysis and designs of composite beams, floors, columns and trusses as per the recommendations of IS codes of practice.
- Apply the concepts for design of multi-storey composite buildings.
- Scope of analysis is restricted to skeletal structures subjected to prescribed dynamic loads.
- Study the concepts of composite construction.

Course Outcomes

After the completion of this course, the students shall be able to:

- Understand the fundamentals of composite construction, and analysis and designs of composite beams.
- Analyse and design the composite floors Illustrate the manufacturing of metal matrix composites and outline the properties and applications.
- Select suitable materials for composite columns,
- Analyse composite trusses and understand connection details.
- Analyse and design the multi-storey composite buildings

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	2	-	3	-	-	1
CO2	2	-	3	-	-	1
CO3	2	-	3	-	-	1
CO4	2	-	3	-	-	1
CO5	2	-	3	-	-	1

UNIT-I

Introduction of composite constructions: Benefits of composite construction - Introduction to IS - BS and Euro codal provisions.

Composite beams: Elastic behaviour of composite beams - No and full interaction cases - Shear connectors - Ultimate load behaviour - Serviceability limits - Effective breadth of flange - Interaction between shear and moment - Basic design consideration and design of composite beams.

UNIT-II

Composite floors: Structural elements - Profiled sheet decking - Bending resistance - Shear resistance - Serviceability criterion - Analysis for internal forces and moments - Design of composite floors.

UNIT-III

Composite columns: Materials - Concrete filled circular tubular sections - Non-dimensional slenderness - Local buckling of steel sections - Effective elastic flexural stiffness - Resistance of members to axial compressions - Composite column design - Fire resistance.

UNIT-IV

Composite trusses: Design of truss - Configuration - Truss members - Analysis and design of composite trusses and connection details.

UNIT-V

Design of multi-storey composite buildings: Design basis - Load calculations - Design of composite slabs with profile decks - Composite beam design - Design for compression members - Vertical cross bracings - Design of foundation.

References:

1. R.P. Johnson, "Composite Structures of Steel and Concrete - Beams, Slabs, Columns and Frames in Buildings", Blackwell Publishing, Malden, USA, 2004.
2. "INSDAG Teaching Resources for Structural Steel Design", Vol-2, Institute for Steel Development and Growth Publishers, Calcutta, India.
3. "INSDAG Handbook on Composite Construction – Multi-Storey Buildings", Institute for Steel Development and Growth Publishers, Calcutta, India.
4. "INSDAG Design of Composite Truss for Building", Institute for Steel Development and Growth Publishers, Calcutta, India.
5. "INSDAG Handbook on Composite Construction – Bridges and Flyovers", Institute for Steel Development and Growth Publishers, Calcutta, India.
6. IS: 11384-1985, "Code of Practice for Composite Construction in Structural Steel and Concrete", Bureau of Indian Standards, New Delhi, 1985.

OE 941 BM**MEDICAL ASSISTIVE DEVICES****Pre-requisites**

L	T	P	C
3	-	-	3

Evaluation**SEE**

60 Marks

CIE

40 Marks

Course Objectives :

The course is taught with the objectives of enabling the student to:

- 1 To extend knowledge of the amputee, of lost and remaining functions affecting locomotion, and to collect information on the best possible medical treatment.
- 2 To improve fitting techniques and practices, including training, so that existing devices might be used with greater comfort and function.
- 3 To develop improved lower-extremity devices

Course Outcomes :

On completion of this course, the student will be able to :

- CO-1** Apply fundamental knowledge of engineering in rehabilitation
- CO-2** Apply analytical skills to assess and evaluate the need of the end-user
- CO-3** Develop self-learning initiatives and integrate learned knowledge for problem solving
- CO-4** Understand the basics of robotics and apply their principles in developing prosthetics
- CO-5** Apply the knowledge of computers in solving rehabilitation problems

Course outcome	Program Outcome					
	PO-1	PO-2	PO-3	PO-4	PO-5	PO-6
CO-1	2	1	3	2	1	1
CO-2	3	2	1	1	2	-
CO-3	2	2	2	3	2	1
CO-4	1	3	1	2	1	1
CO-5	1	1	2	3	2	3

UNIT-I

Introduction to Rehabilitation Engineering, Measurement and analysis of human movement, Disability associated with aging in the workplace and their solutions, clinical practice of rehabilitation engineering.

UNIT-II

Assistive Technology, Seating Biomechanics and systems. Wheeled Mobility: Categories of Wheelchairs. Wheelchair Structure and Component Design. Ergonomics of Wheel chair propulsion. Power Wheelchair Electrical Systems. Control. Personal Transportation. Auxiliary devices and systems.

UNIT-III

Sensory augmentation and substitution: Visual system: Visual augmentation. Tactual vision substitution, Auditory vision substitution; Auditory system: Auditory augmentation. Cochlear implantation, Visual auditory substitution, Tactual auditory substitution, Tactual system: Tactual augmentation. Tactual substitution. Measurement tools and processes: fundamental principles, structure, function; performance and behavior. Subjective and objective measurement methods.

UNIT-IV

Rehabilitation Robotics, Major Limb Prosthetic Devices, Orthotic Devices, Types of orthotics and prosthetics, Intelligent prosthetic Knee, Prosthetic Hand, Controlled orthotics and prosthetics FES system, Restoration of Hand function, Restoration of standing and walking, Myo-electric Hand.

UNIT-V

Augmentative and Alternative communication technology, Computer applications in Rehabilitation Engineering, telecommunications, and Web Accessibility.

Suggested Reading:

- 1 Robinson C.J., *Rehabilitation Engineering*, CRC Press, 1995.
- 2 Ballabio E., et al., *Rehabilitation Technology*, IOS Press, 1993.
- 3 Rory A Cooper, Hisaichi Ohnabe, Douglas A. Hobson, *Series in medical physics and biomedical engineering: An introduction to rehabilitation engineering*, Taylor and Francis Group, London, 2007.
- 4 Joseph D. Bronzino *The biomedical engineering handbook -biomedical engineering fundamentals*, 3rdEd., CRC Press, Taylor & Francis Group, London, 2006.

OE 942 BM**MEDICAL IMAGING TECHNIQUES**

Pre-requisites			L	T	P	C
			3	-	-	3
Evaluation	SEE	60 Marks	CIE		40 Marks	

Course Objectives :

The course is taught with the objectives of enabling the student to:

- 1 To familiarize the students with various medical imaging modalities.
- 2 To make learners understand the principles, detectors and operating procedures of X-ray, CT, MRI, ultrasound, PET and SPECT.
- 3 To make the students learn the advantages, disadvantages and hazards of various medical imaging equipment.

Course Outcomes :

On completion of this course, the student will be able to :

- CO-1** Interpret the working principle and operating procedure and applications of X-ray equipment.
- CO-2** Understand the image reconstruction techniques and applications of CT.
- CO-3** Summarize the image acquisition and reconstruction techniques in MRI.
- CO-4** Comprehend the working principle, modes and medical applications of ultrasound imaging.
- CO-5** Examine the operation and applications of PET, SPECT and radio nuclide instrumentation.

Course outcome	Program Outcome					
	PO-1	PO-2	PO-3	PO-4	PO-5	PO-6
CO-1	2	1	3	2	1	1
CO-2	3	2	1	1	2	-
CO-3	2	2	2	3	2	1
CO-4	1	3	1	2	1	1
CO-5	1	1	2	3	2	3

UNIT-I

X ray Imaging: Electromagnetic spectrum, Production of X-rays, X-ray tubes- Stationary and Rotating Anode types, Block diagram of an X-Ray Machine, Collimators and Grids, Timing and Exposure controls. X-Ray Image visualization-Films, Fluorescent screens, Image Intensifiers.

Dental X-Ray machines, Portable and mobile X-Ray units, Mammographic X-Ray equipment, Digital Radiography and flat panel detectors.

Radiation safety, ALARA principle, Dose units and dose limits, Radiation dosimeters and detectors.

UNIT – II

Computed Tomography: Basic principles, CT number scale, CT Generations. Major sub systems- Scanning system, processing unit, viewing unit, storage unit. Need and Principle of sectional imaging, 2D image reconstruction techniques - Iteration and Fourier methods. Applications of CT - Angio, Osteo, Dental, Perfusion (Body & Neuro), Virtual Endoscopy, Coronary Angiography.

UNIT – III

Magnetic Resonance Imaging: Principles of NMR imaging systems, Image reconstruction techniques-Relaxation processes, imaging/ pulse sequences. Sub systems of an NMR imaging system, NMR detection system, types of coils, biological effects and advantages of NMR imaging.

Functional MRI - The BOLD effect, intra and extra vascular field offsets, source of T2* effects, Creating BOLD contrast sequence optimization sources and dependences of physiological noise in fMRI.

UNIT – IV

Ultrasound Imaging: - Principles of image formation -Imaging principles and instrumentation of A-mode, B-Mode, Gating Mode, Transmission mode and M-mode. Basics of multi-element linear array scanners, Digital scan conversion.

Doppler Ultrasound and Colour Doppler imaging, Image artifacts, Biological effects, Ultrasound applications in diagnosis, therapy and surgery.

UNIT– V

Nuclear Medicine–Radioisotopes in medical diagnosis, Basic instrumentation- Radiation detectors, Pulse height analyzer, Rectilinear scanner, Gamma camera.

Emission Computed Tomography (ECT), Principle and instrumentation of Single Photon Emission Computed Tomography(SPECT) and Positron Emission Tomography (PET).

Comparison of SPECT, PET and combined PET/ X-ray CT.

Suggested Reading:

- 1 Khandpur R.S., *Handbook of Biomedical Instrumentation*, Tata McGraw Hill, 2016.
- 2 S Webb, "*The Physics of Medical Imaging*", Adam Highler, Bristol Published by CRC Press, 1988.
- 3 A C Kak, "*Principle of Computed Tomography*", IEEE Press New York, 1988.
- 4 Hykes, Heorick, Starchman, *Ultrasound physics and Instrumentation* MOSBY year book, 2ndEd. 1992.
- 5 Stewart C. Bushong, *Magnetic Resonance Imaging- physical and biological principles*, MOSBY, 2nd Ed., 1995.

OE 941 LA**INTELLECTUAL PROPERTY RIGHTS**

Pre-requisites			L	T	P	C
			3	-	-	3
Evaluation	SEE	60 Marks	CIE		40 Marks	

Course Objectives :

The course is taught with the objectives of enabling the student to:

- 1 Acquaint the students with basics of intellectual property rights with special reference to Indian Laws and its practices.
- 2 Compare and contrast the different forms of intellectual property protection in terms of their key differences and similarities.
- 3 Provide an overview of the statutory, procedural, and case law underlining these processes and their interplay with litigation.

Course Outcomes :

On completion of this course, the student will be able to :

- CO-1** Understand the concept of intellectual property rights.
CO-2 Develop proficiency in trademarks and acquisition of trade mark rights.
CO-3 Understand the skill of acquiring the copy rights, ownership rights and transfer.
CO-4 Able to protect trade secrets, liability for misappropriations of trade secrets.
CO-5 Apply the patents and demonstration of case studies.

Course outcome	Program Outcome					
	PO-1	PO-2	PO-3	PO-4	PO-5	PO-6
CO-1	2	1	3	2	1	1
CO-2	3	2	1	1	2	-
CO-3	2	2	2	3	2	1
CO-4	1	3	1	2	1	1
CO-5	1	1	2	3	2	3

UNIT-I

Nature of Intellectual Property: Patents, Designs, Trade and Copyright. Process of Patenting and Development: technological research, innovation, patenting, development. International Scenario: International cooperation on Intellectual Property. Procedure for grants of patents, Patenting under PCT.

UNIT – II

Trade Marks: Purpose and function of trademarks, acquisition of trade mark rights, protectable matter, selecting, and evaluating trade mark, trade mark registration processes.

UNIT – III

Law of copy rights: Fundamental of copy right law, originality of material, rights of reproduction, rights to perform the work publicly, copy right ownership issues, copy right registration, notice of copy right, international copy right law. Law of patents: Foundation of patent law, patent searching process, ownership rights and transfer.

UNIT – IV

Trade Secrets: Trade secrete law, determination of trade secrete status, liability for misappropriations of trade secrets, protection for submission, trade secrete litigation. Unfaircompetition: Misappropriation right of publicity, false advertising.

UNIT– V

New Developments in IPR: Administration of Patent System. New developments in IPR; IPR of Biological Systems, Computer Software etc. Traditional knowledge Case Studies, IPR and IITs.

Suggested Reading:

- 1 Halbert, “Resisting Intellectual Property”, Taylor & Francis Ltd, 2007.
- 2 “Mayall, “Industrial Design”, McGraw Hill,1992
- 3 “Nebel, “Product Design”, McGraw Hill,1974.
- 4 “Asimov, “Introduction to Design”, Prentice Hall,1962.
- 5 “Robert P. Merges, Peter S. Menell, Mark A. Lemley,
“Intellectual Propertyin New Technological Age”,2016.
- 6 T. Ramappa, “Intellectual Property Rights Under WTO”, S. Chand,2008

EE171

MINI PROJECT

Instruction	:	4 hours per week
Duration of SEE	:	--
SEE	:	--
CIE	:	50 Marks
Credits	:	2

Course Objectives

- To review available literature and formulate structural engineering problems
- To learn the technique of writing reports and prepare presentation

Course Outcomes

After the completion of this course, the students shall be able to:

1. Formulate a specific problem and give solution
2. Develop model/models either theoretical/practical/numerical form
3. Solve, interpret/correlate the results and discussions
4. Conclude the results obtained
5. Write the documentation in standard format

Guidelines

- As part of the curriculum in the II- semester of the programme each student shall do a mini project, generally comprising about three to four weeks of prior reading, twelve weeks of active research, and finally a presentation of their work for assessment.
- Each student will be allotted to a faculty supervisor for mentoring.
- Mini projects should present students with an accessible challenge on which to demonstrate competence in research techniques, plus the opportunity to contribute something more original.
- Mini projects shall have inter-disciplinary/ industry relevance.
- The students can select a mathematical modelling based/Experimental investigations or Numerical modelling
- All the investigations should be clearly stated and documented with the reasons/explanations.
- The mini-project shall contain a clear statement of the research objectives, background of work, literature review, techniques used, prospective deliverables, and detailed discussion on results, conclusions and reference

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	3	2	-	-	2
CO2	3	3	2	-	-	2
CO3	3	3	2	-	-	2
CO4	3	3	2	-	-	2
CO5	3	3	2	-	-	2

Departmental committee: Supervisor and a minimum of two faculty members

Guidelines for awarding marks in CIE (Continuous Internal Evaluation): Max. Marks: 50		
Evaluation by	Max. Marks	Evaluation Criteria / Parameter
Supervisor	20	Progress and Review
	05	Report
Departmental Committee	05	Relevance of the Topic
	05	PPT Preparation
	05	Presentation
	05	Question and Answers
	05	Report Preparation

EE152**DRIVES LABORATORY - II**

Instruction: 2 hours per week

CIE: 50 marks

Credits: 1

Course Objectives

- To understand and implement DSP and FPGA code for generating pulses for converters.
- To Analyze and design switching pulses for three-phase inverters fed R Load, Induction motor and converter fed SRM.
- To Analyze and design switching pulses for converter fed BLDC and DC Motors.

Course Outcomes:

After completion of this course, the students shall be able to:

1. Write DSP and FPGA code for generating pulses for converters.
2. Implement Hardware experiment DSP controlled for three-phase inverters fed R Load, Induction motor and converter fed SRM.
3. Implement Hardware experiment on FPGA controlled converter fed DC Motor and BLDC Motor.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	3	2	3	-	2
CO2	3	3	2	3	-	2
CO3	3	3	2	3	-	2
CO4	3	3	2	3	-	2
CO5	3	3	2	3	-	2

List of Experiments

1. Generation of Fixed PWM pulses using DSP-28335 with Code composer studio (CCS).
2. Generation of pulses for 180⁰ conduction mode of 3 phase Inverter using DSP-28335 with CCS.
3. Generation of Fixed PWM pulses using DSP-28335 with MATLAB.
4. Generation of Sinusoidal PWM pulses using DSP-28335 with MATLAB.
5. Speed control of chopper fed DC Motor using FPGA

6. Six step operation of 3 phase Inverter with Resistive Load Using DSP 28335.
7. DSP 28335 based speed control of 3 phase Inverter fed Induction motor using SPWM.
8. DSP 28335 based speed control of 3 phase 3 Level Inverter fed Induction motor using SPWM.
9. Three phase Semi and Full Converter with R and RL Load.
10. Speed control of BLDC Motor using FPGA
11. Speed control of SRM Motor using DSP

EE153

DRIVES LABORATORY – III

Artificial Intelligence lab for Industrial Drives and Control

Instruction: 2 hours per week

CIE: 50 marks

Credits: 1

Course Objectives

- To understand and implement Fuzzy logic.
- To implement Fuzzy logic tool box using MATLAB tool box.
- To train ANN network.
- To implement the ANN using MATLAB tool box
- Testing and Implementation of benchmark functions using GA/PSO/LP/NLP

Course Outcomes:

After completion of this course, the students shall be able to:

- Implement Fuzzy logic tool box using MATLAB tool box.
- Train any network using ANN.
- Implement Fuzzy logic tool box using MATLAB tool box
- Use the benchmark tested functions for different applications.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	3	2	-	-	-
CO2	3	3	2	-	-	-
CO3	3	3	2	-	-	-
CO4	3	3	2	-	-	-
CO5	3	3	2	-	-	-

1. Implementation of Fuzzy Logic: developing membership functions, fuzzification, defuzzification and rule base processes

2. Implementation of Fuzzy Logic controller using tool box

3. Implementation of Fuzzy PID controller.

4. Implementation of Artificial Neural Network: data generation, training and validation

5. Implementation of ANN using tool box. ANN Based Speed Control of Solar Powered DC Motor
6. Developing program for Genetic algorithm process: population generation, selection, cross over and mutation.
7. Testing GA on benchmark functions using GA tool box.

8. Conventional LP and NLP using optimization tool box and testing on benchmark functions.

9. Developing program for Particle swarm Optimization and testing on benchmark functions.

10. THD minimization in Multilevel inverters using GA/PSO/LP/NLP

AC030EE**ENGINEERING RESEARCH METHODOLOGY IN ELECTRICAL ENGINEERING**

Instruction: 3 periods per week
CIE: 40 marks

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- To learn the research types, methodology and formulation.
- To know the sources of literature, survey, review and quality journals.
- To understand the research design for collection of research data.
- To understand the research data analysis, writing of research report and grant proposal.

Course Outcomes:

After the completion of this course, students shall be able to:

1. Know the importance of research, the method and the methodology adopted.
2. Do a proper research design for a given research topic.
3. Do the literature survey and the review.
4. Analyze and solve the statistical methods used for the research.
5. Write technical report, research proposals.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	3	-	-	-	2
CO2	3	3	-	-	-	2
CO3	3	3	-	-	-	2
CO4	3	3	-	-	-	2
CO5	3	3	-	-	-	2

UNIT - I

Research Methodology: Objectives and Motivation of Research, Types of Research, Research Approaches, Significance of Research, Research Methods versus Methodology, Research and Scientific Method, Importance of Research Methodology, Research Process, Criteria of Good Research, Problems Encountered by Researchers in India, Benefits to the society in general.

Defining the Research Problem: Definition of Research Problem, Problem Formulation, Necessity of Defining the Problem, Techniques involved in Defining a Problem.

UNIT - II

Literature Survey: Importance of Literature Survey, Sources of Information, Assessment of Quality of Journals and Articles, Information through Internet.

Literature Review: Need of Review, Guidelines for Review, Record of Research Review. A review of the smart grid concept for electrical power system, Power Electronics Converters for the Internet of Energy, Direct Torque Control of Induction Machine: A Review.

UNIT - III

Research Design: Meaning of Research Design, Need of Research Design, Feature of a Good Design, Important concepts related to Research Design, Different Research Designs, Basic Principles of Experimental Design, Developing a Research Plan, Design of Experimental Set-up, Use of Standards and Codes.

UNIT - IV

Data Collection and Analysis: Collection of primary data, Secondary data, Data organization, Methods of data grouping, Diagrammatic representation of data, Graphic representation of data. Sample Design, Need for sampling, some important sampling definitions, Estimation of population, Role of Statistics for Data Analysis, Parametric V/s Non-Parametric methods, Descriptive Statistics, Processing and Analysis of Data.

UNIT - V

Research Report Writing, Publishing: Format of the Research report, Style of writing report, References/Bibliography/Webliography, Preparing the List of Works, Cited, Technical paper writing/Journal report writing. Considerations when selecting a target journal, submitting a manuscript, how to respond to editors and referees, A process for preparing a manuscript. Plagiarism and Academic Integrity.

Research Proposal Preparation: Funding agencies in India and across the Globe, writing a Research Proposal and Research Report, Writing Research Grant Proposal: Minor and Major Research proposals (UGC and AICTE).

References

1. C.R Kothari, Research Methodology, Methods & Technique; New Age International Publishers, 2004
2. R. Ganesan, Research Methodology for Engineers, MJP Publishers, 2011
3. Vijay Upagade and AravindShende, Research Methodology, S. Chand & Company Ltd., New Delhi, 2009
4. P.Ramdas and Wilson Aruni; Research and Writing across the disciplines; MJP Publishers, Chennai, 2009.
5. Margaret Cargill and Patrick O'Connor: Writing Scientific Research Articles Strategy and Steps, A John Wiley & Sons, Ltd., Publication, 2009.
6. MLA Handbook for Writers of Research Papers, The modern language association of America, New York 2009.

AC031**ENGLISH FOR RESEARCH PAPER WRITING**

Instruction: 3 periods per week

Duration of SEE: 3 hours

CIE: 40 marks

SEE: 60 marks

Course Objectives: To expose the students to...

- Features of Academic writing; different kinds of Academic writing
- Some academic writing skills; the research process; the structure of a research document

Course Outcomes: At the end of the course, the students would be equipped with the knowledge and skills relating to ...

1. Academic writing features; Academic writing kinds; Important academic writing skills
2. The process of research; general research document structure

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	3	-	-	-	2
CO2	3	3	-	-	-	2

UNIT I: Features of Academic Writing

Language: Clear, Correct, Concise, Inclusive; **Tone:** Formal, Objective, Cautious;
Style: Appropriate, Accurate, Organized; **Ethics:** Honesty, Integrity, Responsibility, Accountability

UNIT II: Kinds of Academic Writing

Essays, Reports, Reviews, Abstracts, Proposals

UNIT III: Academic Writing Skills

Paraphrasing; Summarizing; Quoting; Rewriting; Expansion

UNIT IV: Research Process

Selection of Topic, Formulation of Hypothesis, Collection of Data, Analysis of Data, Interpretation of Data, Presentation of Data

UNIT V: Structure of a Research Document

Title, Abstract, Introduction, Literature Survey, Methodology, Discussion, Findings/Results, Conclusion, Documenting Sources (IEEE style)

Suggested Reading

1. Bailey, S. (2014). *Academic writing: A handbook for international students*. Routledge.
2. Gillett, A., Hammond, A., & Martala, M. (2009). *Inside track: Successful academic writing*. Essex: Pearson Education Limited.
3. Griffin, G. (2006). *Research methods for English studies*. Edinburgh: Edinburgh University Press.

4. Silyn-Roberts, Heather. (2013). *Writing for Science and Engineering: Papers, Presentations and Reports* (2nd ed.). Elsevier.
5. Lipson, Charles (2011). *Cite right: A quick guide to citation styles; MLA, APA, Chicago, the sciences, professions, and more* (2nd ed.). Chicago[u.a.]: University of Chicago Press.

AC032**DISASTER MITIGATION & MANAGEMENT**

Instruction: 3 periods per week

Duration of SEE: 3 hours

CIE: 40 marks

SEE: 60 marks

Course Objectives

- To impart knowledge in students about the nature, causes, consequences and mitigation measures of the various natural disasters
- To enable the students to understand risks, vulnerabilities and human errors associated with human induced disasters
- To enable the students to understand and assimilate the impacts of any disaster on the affected area depending on its position/ location, environmental conditions, demographic, etc.

Course Outcomes

After the completion of this course, the students shall be able to:

1. Learn to demonstrate a critical understanding of key concepts in disaster risk reduction and Humanitarian response
2. Critically evaluate disaster risk reduction and humanitarian response policy and Practice from multiple perspectives.
3. Develop an understanding of standards of humanitarian response and practical relevance in specific types of disasters and conflict situations.
4. Critically understand the strengths and weaknesses of disaster management approaches, planning and programming in different countries, particularly their home country or the countries they work in.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-	-	2
CO2	3	-	3	-	-	2
CO3	3	-	3	-	-	2
CO4	3	-	3	-	-	2

UNIT I

Introduction: Disaster Definition, Factors and Significance; Difference between Hazard and Disaster; Natural and Manmade Disasters: Difference, Nature, Types and Magnitude.

UNIT II

Repercussions of Disasters and Hazards: Economic Damage, Loss of Human and Animal Life, Destruction of Ecosystem.

Natural Disasters: Earthquakes, Volcanisms, Cyclones, Tsunamis, Floods, Droughts and Famines, Landslides and Avalanches, Man-made disaster: Nuclear Reactor Meltdown, Industrial Accidents, Oil Slicks and Spills, Outbreaks of Disease and Epidemics, War and

Conflicts.

UNIT III

Disasters Prone Areas in India: Study of Seismic Zones; Areas Prone to Floods and Droughts, Landslides and Avalanches; Areas Prone to Cyclonic and Coastal Hazards with Special Reference to Tsunami; Post-Disaster Diseases and Epidemics

UNIT IV

Disaster Preparedness: Monitoring of Phenomena Triggering a Disaster or Hazard; Evaluation of Risk: Application of Remote Sensing, Data from Meteorological and Other Agencies, Media Reports: Governmental and Community Preparedness.

UNIT V

Disaster Risk: Concept and Elements, Disaster Risk Reduction, Global and National Disaster Risk Situation. Techniques of Risk Assessment, Global Co-Operation in Risk Assessment and Warning, People's Participation in Risk Assessment. Strategies for Survival.

Disaster Mitigation: Meaning, Concept and Strategies of Disaster Mitigation, Emerging Trends in Mitigation. Structural Mitigation and Non-Structural Mitigation, Programs of Disaster Mitigation in India.

References

- 1 R. Nishith, Singh AK, "Disaster Management in India: Perspectives, issues and strategies", New Royal Book Company.
- 2 Sahni, Pardeep et al. (Eds.), "Disaster Mitigation Experiences and Reflections", Prentice Hall of India, New Delhi.
- 3 Goel S. L., "Disaster Administration and Management Text and Case Studies", Deep & Deep Publication Pvt. Ltd., New Delhi.

AC033**SANSKRIT FOR TECHNICAL KNOWLEDGE**

Instruction: 3 periods per week

CIE: 40 marks

Duration of SEE: 3 hours

SEE: 60 marks

Course Objectives

- To get a working knowledge in illustrious Sanskrit, the scientific language in the world
- To learn Sanskrit to improve brain functioning and enhancing the memory power
- To learn Sanskrit to develop the logic in mathematics, science & other subjects
- The engineering scholars equipped with Sanskrit will be able to explore the huge knowledge from ancient Indian literature

Course Outcomes

After the completion of this course, the students shall be able to:

1. Understand basic Sanskrit language
2. Understand ancient Sanskrit literature about science & technology
3. Develop logic in students, Sanskrit being a logical language

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	-	3	-	-	-	2
CO2	3	3	-	-	-	2
CO3	3	3	-	-	-	2

Syllabus Contents**UNIT-I**

- Alphabets in Sanskrit,
- Past/Present/Future Tense,
- Simple Sentences

UNIT-II

- Order
- Introduction of roots
- Technical information about Sanskrit Literature

UNIT-III

- Technical concepts of Engineering-Electrical, Mechanical,Architecture, Mathematics

References:

- 1 “Abhyaspustakam” – Dr. Vishwas, Samskrita-Bharti Publication, New Delhi
- 2 “Teach Yourself Sanskrit” Prathama Deeksha-VempatiKutumbshastri,

RashtriyaSanskritSansthanam, New Delhi Publication

- 3 “India’s Glorious Scientific Tradition” Suresh Soni, Ocean books (P) Ltd., New Delhi.

AC034**VALUE EDUCATION**

Instruction: 3 periods per week
CIE: 40 marks

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- Understand the need for and importance of Values for self-development and for National development.
- Imbibe good human values and Morals
- Cultivate individual and National character.

Course Outcomes

After the completion of this course, the students shall be able to:

1. Gain necessary Knowledge for self-development
2. Learn the importance of Human values and their application in day-to-day professional life.
3. Develop overall personality.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	2	3	-	-	-	2
CO2	2	3	-	-	-	2
CO3	2	3	-	-	-	2

Syllabus Contents**UNIT I**

- Values and self-development –Social values and individual attitudes.
- Work ethics, Indian vision of humanism.
- Moral and non- moral valuation. Standards and principles.
- Value judgments

UNIT II

- Importance of cultivation of values.
- Sense of duty. Devotion, Self-reliance. Confidence, Concentration.
- Truthfulness, Cleanliness.
- Honesty, Humanity. Power of faith, National Unity.
- Patriotism. Love for nature, Discipline.

UNIT III

- Personality and Behavior Development - Soul and Scientific attitude.
- Positive Thinking. Integrity and discipline.
- Punctuality, Love and Kindness.
- Avoid fault Thinking.
- Free from anger, Dignity of labour.
- Universal brotherhood and religious tolerance.
- True friendship.
- Happiness Vs suffering, love for truth.
- Aware of self-destructive habits.
- Association and Cooperation.

UNIT IV

- Doing best for saving nature
- Character and Competence –Holy books vs Blind faith.
- Self-management and Good health.
- Science of reincarnation.
- Equality, Nonviolence, Humility, Role of Women.
- All religions and same message.
- Mind your Mind, Self-control.
- Honesty, Studying effectively

References

- 1 Chakroborty, S.K., “*Values & Ethics for organizations Theory and practice*”, Oxford University Press, New Delhi, 1998.

AC035**STRESS MANAGEMENT BY YOGA**

Instruction: 3 periods per week
CIE: 40 marks

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- Creating awareness about different types of stress and the role of yoga in the management of stress.
- Promotion of positive health and overall wellbeing (Physical, mental, emotional, social and spiritual).
- Prevention of stress related health problems by yoga practice.

Course Outcomes

After the completion of this course, the students shall be able to:

1. Understand yoga and its benefits.
2. Enhance Physical strength and flexibility.
3. Learn to relax and focus.
4. Relieve physical and mental tension through asanas.
5. Improve work performance and efficiency.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	-	2	-	-	-	1
CO2	-	2	-	-	-	1
CO3	-	2	-	-	-	1
CO4	-	2	-	-	-	1
CO5	-	2	-	-	-	1

UNIT I

Introduction: Definition of **Stress** – Types of stress: Acute and chronic - Stressors – Definition of **Yoga** from various sources – Types of yoga – Karma yoga, Gnana yoga, Bhakti yoga and Raja yoga – Concept of Bhagavad Geeta - Yoga versus exercise –Basics of Physiology and Psychology – Brain and its parts – CNS and PNS – HPA axis – Sympathetic and Para sympathetic nervous systems – Fight and Flight mechanism - Relationship between stress and yoga.

UNIT II

Ashtanga Yoga: Do's and Don'ts in life: (i) **Yam** - Ahinsa, satya, astheya, bramhacharya and aparigraha (ii) **Niyam**-Shaucha, santosh, tapa, swadhyay, ishwarpranidhan (iii) **Asana** (iv) **Pranayama** (v) **Prathyahara** (vi) **Dharana** (vii) **Dhyana** (viii) **Samadhi** – Illustrations of eight steps of Ashtanga yoga.

UNIT III

Asana and Stress: Definition of Asana from Pathanjali – Origin of various names of asanas - Various yoga poses and their benefits for mind & body – Sequence of performing asanas: Standing, sitting, lying down on stomach, lying down on back and inverted postures – Activation of Annamayakosha – Effect on various chakras, systems and glands thereby controlling the stress levels through the practice of asanas.

UNIT IV

Pranayama and Stress: Definition of pranayama from Shankaracharya - Regularization of breathing techniques and its effects - Types of pranayama – Heat generating and cold generating techniques – Pranayama versus chakras and systems – Breathing techniques versus seasons - Anger and breathing rate – Activation of pranamayakosha – Pranayama as the bridge between mind and body – Stress control through pranayama.

UNIT V

Dhyana and Stress: Distinction between Dhyana and Dharana– Preparation for Dhyana through prathyahara and dharana – Activation of Vignanamayakosha – Types of mind: conscious, superconscious and subconscious – Activation of manomayakosha through Dhyana – Silencing the mind thereby controlling the stress levels.

References

- 1 *'Yogic Asanas for Group Training-Part-I'* : Janardan Swami YogabhyasiMandal, Nagpur
- 2 *"Rajayoga or Conquering the Internal Nature"* by Swami Vivekananda, AdvaitaAshrama (Publication Department), Kolkata
- 3 *"Light on Yoga"* by BKS Iyengar
- 4 *"The search for happiness and bliss"* by Swami Sarvapriyananda on you tube – <https://youtu.be/xfywJTPkw7Y>
- 5 *"Mastering the mind"* by SwaminiVimalananda on you tube - <https://youtu.be/EXniWH9DMF8>

AC036**PERSONALITY DEVELOPMENT THROUGH LIFE ENLIGHTENMENT SKILLS**

Instruction: 3 periods per week

Duration of SEE: 3 hours

CIE: 40 marks

SEE: 60 marks

Course Objectives

- To learn to achieve the highest goal happily
- To become a person with stable mind, pleasing personality and determination
- To awaken wisdom in students

Course Outcomes

After the completion of this course, the students shall be able to:

1. Develop their personality and achieve their highest goal of life.
2. Lead the nation and mankind to peace and prosperity.
3. Practice emotional self-regulation.
4. Develop a positive approach to work and duties.
5. Develop a versatile personality.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	-	2	-	-	-	1
CO2	-	2	-	-	-	1
CO3	-	2	-	-	-	1
CO4	-	2	-	-	-	1
CO5	-	2	-	-	-	1

UNIT I

- Neetisatakam-Holistic development of personality
- Verses- 19,20,21,22 (wisdom)
- Verses- 29,31,32 (pride & heroism)
- Verses- 26,28,63,65 (virtue)
- Verses- 52,53,59 (don't's)
- Verses- 71,73,75,78 (do's)

UNIT II

- Approach to day-to-day work and duties.
- Shrimad Bhagwad Geeta: Chapter 2-Verses 41, 47,48,
- Chapter 3-Verses 13, 21, 27, 35, Chapter 6-Verses 5,13,17, 23, 35,
- Chapter 18-Verses 45, 46, 48.

UNIT III

- Statements of basic knowledge.
- Shrimad Bhagwad Geeta: Chapter2-Verses 56, 62, 68
- Chapter 12 -Verses 13, 14, 15, 16, 17, 18
- Personality of Role model. Shrimad Bhagwad Geeta:
- Chapter2-Verses 17, Chapter 3-Verses 36, 37, 42,
- Chapter 4-Verses 18, 38, 39
- Chapter18 – Verses 37, 38, 63

References

- 1 Swami SwarupanandaAdvaita Ashram “*Srimad Bhagavad Gita*”, (Publication Department), Kolkata
- 2 P.Gopinath, “*Bhartrihari’s Three Satakam (Niti-sringar-vairagya)*”, Rashtriya Sanskrit Sansthanam, New Delhi

AC037**CONSTITUTION OF INDIA**

Instruction: 3 periods per week

CIE: 40 marks

Duration of SEE: 3 hours

SEE: 60 marks

Course Objectives

- Understand the premises informing the twin themes of liberty and freedom from a civil rights perspective
- To address the growth of Indian opinion regarding modern Indian intellectuals' constitutional role
- Entitlement to civil and economic rights as well as the emergence of nationhood in the early years of Indian nationalism.

Course Outcomes

After the completion of this course, the students shall be able to:

1. Discuss the growth of the demand for civil rights in India for the bulk of Indians before the arrival of Gandhi in Indian politics.
2. Discuss the intellectual origins of the framework of argument that informed the conceptualization of social reforms leading to revolution in India.
3. Discuss the circumstances surrounding the foundation of the Congress Socialist Party [CSP] under the leadership of Jawaharlal Nehru
4. The eventual failure of the proposal of direct elections through adult suffrage in the Indian Constitution.
5. Discuss the passage of the Hindu Code Bill of 1956.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	-	2	-	-	-	-
CO2	-	2	-	-	-	-
CO3	-	2	-	-	-	-
CO4	-	2	-	-	-	-
CO5	-	2	-	-	-	-

UNIT I**History of Making of the Indian Constitution:**

- History
- Drafting Committee, (Composition & Working)

UNIT II

Philosophy of the Indian Constitution:

- Preamble
- Salient Features

UNIT III

Contours of Constitutional Rights & Duties:

- Fundamental Rights
- Right to Equality
- Right to Freedom
- Right against Exploitation
- Right to Freedom of Religion
- Cultural and Educational Rights
- Right to Constitutional Remedies
- Directive Principles of State Policy
- Fundamental Duties.

UNIT IV

- Organs of Governance:
- Parliament
- Composition
- Qualifications and Disqualifications
- Powers and Functions
- Executive
- President
- Governor
- Council of Ministers
- Judiciary, Appointment and Transfer of Judges, Qualifications
- Powers and Functions

UNIT V

- Local Administration:
- District's Administration head: Role and Importance,
- Municipalities: Introduction, Mayor and role of Elected Representative, CE of Municipal Corporation.
- Panchayati raj: Introduction, PRI: ZilaPanchayat.
- Elected officials and their roles, CEO ZilaPanchayat: Position and role.
- Block level: Organizational Hierarchy (Different departments),
- Village level: Role of Elected and Appointed officials,
- Importance of grass root democracy

UNIT VI

- Election Commission:
- Election Commission: Role and Functioning.
- Chief Election Commissioner and Election Commissioners.
- State Election Commission: Role and Functioning.
- Institute and Bodies for the welfare of SC/ST/OBC and women.

References

- 1 *“The Constitution of India”*, 1950 (Bare Act), Government Publication.
- 2 Dr. S. N. Busi, *“Dr. B. R. Ambedkar framing of Indian Constitution”*, 1st Edition, 2015.
- 3 M. P. Jain, *“Indian Constitution Law”*, 7th Edn., Lexis Nexis, 2014.
- 4 D.D. Basu, *“Introduction to the Constitution of India”*, Lexis Nexis, 2015.

AC038**PEDAGOGY STUDIES**

Instruction: 3 periods per week
CIE: 40 marks

Duration of SEE: 3 hours
SEE: 60 marks

Course Objectives

- To present the basic concepts of design and policies of pedagogy studies.
- To provide understanding of the abilities and dispositions with regard to teaching techniques, curriculum design and assessment practices and familiarize various theories of learning and their connection to teaching practice.
- To create awareness about the practices followed by DFID, other agencies and other researchers and provide understanding of critical evidence gaps that guides the professional development

Course Outcomes

After the completion of this course, the students shall be able to:

1. Illustrate the pedagogical practices followed by teachers in developing countries both in formal and informal classrooms.
2. Examine the effectiveness of pedagogical practices.
3. Understand the concept, characteristics and types of educational research and perspectives of research.
4. Describe the role of classroom practices, curriculum and barriers to learning.
5. Understand Research gaps and learn the future directions.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	-	2	-	-	-	1
CO2	-	2	-	-	-	1
CO3	-	2	-	-	-	1
CO4	-	2	-	-	-	1
CO5	-	2	-	-	-	1

UNIT I

Introduction and Methodology: Aims and rationale, Policy background, Conceptual framework and terminology - Theories of learning, Curriculum, Teacher education - Conceptual framework, Research questions, Overview of methodology and Searching.

UNIT II

Thematic Overview: Pedagogical practices followed by teachers in formal and informal classrooms in developing countries - Curriculum, Teacher education

UNIT III

Evidence on the Effectiveness of Pedagogical Practices: Methodology for the in-depth stage: quality assessment of included studies - How can teacher education (curriculum and Practicum) and the school curriculum and guidance material best support effective pedagogy? - Theory of change - Strength and nature of the body of evidence for effective pedagogical practices - Pedagogic theory and pedagogical approaches – Teachers attitudes and beliefs and pedagogic strategies.

UNIT IV

Professional Development: Alignment with classroom practices and follow up support - Support from the head teacher and the community – Curriculum and assessment - Barriers to learning: Limited resources and large class sizes.

UNIT V

Research Gaps and Future Directions: Research design – Contexts – Pedagogy - Teacher education - Curriculum and assessment – Dissemination and research impact.

References

- 1 Ackers J, Hardman F, “*Classroom Interaction in Kenyan Primary Schools, Compare*”, 31 (2): 245 – 261, 2001.
- 2 Agarwal M, “*Curricular Reform in Schools: The importance of evaluation*”, *Journal of Curriculum Studies*, 36 (3): 361 – 379, 2004.
- 3 Akyeampong K, “*Teacher Training in Ghana – does it count? Multisite teacher education research project (MUSTER)*”, Country Report 1. London: DFID, 2003.
- 4 Akyeampong K, Lussier K, Pryor J, Westbrook J, “*Improving teaching and learning of Basic Maths and Reading in Africa: Does teacher Preparation count?*” *International Journal Educational Development*, 33 (3): 272- 282, 2013.
- 5 Alexander R J, “*Culture and Pedagogy: International Comparisons in Primary Education*”, Oxford and Boston: Blackwell, 2001.
- 6 Chavan M, Read India: “*A mass scale, rapid, learning to read campaign*”, 2003
- 7 www.pratham.org/images/resource%20working%20paper%202.pdf.

EE181**MAJOR PROJECT PHASE - I**

Instruction	: 20 hours per week
Duration of SEE	: --
SEE	: --
CIE	: 100 Marks
Credits	: 10

Course Objectives

- To identify the research problem.
- To perform literature survey.

Course Outcomes

After the completion of this course, the students shall be able to:

1. Exposed to self-learning of various topics.
2. Learn to survey the literature such as books, journals and contact resource persons for the selected topic of research.
3. Learn to write technical reports.
4. Develop oral and written communication skills to present.
5. Defend their work in front of technically qualified audience

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	3	2	-	-	2
CO2	3	3	2	-	-	2
CO3	3	3	2	-	-	2
CO4	3	3	2	-	-	2
CO5	3	3	2	-	-	2

Guidelines

- The Project work will preferably be a problem with research potential and should involve scientific research, design, generation/collection and analysis of data, determining solution and must preferably bring out the individual contribution.
- Seminar should be based on the area in which the candidate has undertaken the dissertation work.
- The CIE shall include reviews and the preparation of report consisting of a detailed problem statement and a literature review.
- The preliminary results (if available) of the problem may also be discussed in the report.
- The work must be presented in front of the committee consists of Chairperson-BoS, Osmania University and Head, Supervisor & Project coordinator from the respective Department of the Institute.

- The candidate must be in regular contact with his supervisor and the topic of dissertation must be mutually decided by the guide and student.

Guidelines for awarding marks in CIE (Continuous Internal Evaluation): Max. Marks: 100		
Evaluation by	Max. Marks	Evaluation Criteria / Parameter
Supervisor	30	Problem formulation
	10	Literature review
	10	Proposed methodology
	10	Documentation
	50	Total
Departmental Committee (Chairperson BoS, Osmania University and Head, Supervisor & Project coordinator from the respective department of the institution)	15	Relevance of the Topic
	15	PPT Preparation
	10	Documentation
	10	Question and Answers
	50	Total

Note: The Supervisor has to assess the progress of the student regularly.

***The student has to work a minimum of 20 hours/week at Dissertation – I**

EE182**MAJOR PROJECT PHASE - II**

Instruction	: 32 hours per week
Duration of SEE	: --
SEE	: 100 Marks
CIE	: 100 Marks
Credits	: 16

Course Objectives

- To identify the research problem.
- To perform literature survey.

Course Outcomes

1. Use different experimental techniques and will be able to use different software/ computational /analytical tools.
2. Design and develop an experimental set up/ equipment/test rig.
3. Conduct tests on existing set ups/equipment's and draw logical conclusions from the results after analysing them.
4. Either work in a research environment or in an industrial environment.
5. Conversant with technical report writing and will be able to present and convince their topic of study to the engineering community.

Programme Articulation Matrix

Course outcome	Programme outcome					
	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	3	2	-	-	2
CO2	3	3	2	-	-	2
CO3	3	3	2	-	-	2
CO4	3	3	2	-	-	2
CO5	3	3	2	-	-	2

Guidelines:

- It is a continuation of Major Project Phase – I started in semester - III.
- The student has to submit the report in prescribed format and also present a seminar.
- The dissertation should be presented in standard format as provided by the department.
- The candidate must prepare a detailed project report consisting of introduction of the problem, problem statement, literature review, objectives of the work, methodology (experimental set up or numerical details as the case may be) of solution and results and discussion.
- The report must bring out the conclusions of the work and future scope for the study. The work must be presented in front of the examiners panel consisting of an approved external examiner and Chairperson BoS, & Head of the department and Supervisor from the Institute.
- The candidate must be in regular contact with his/her Supervisor / Co- Supervisor

Guidelines for awarding marks in CIE : Max. Marks: 100		
Evaluation by	Max. Marks	Evaluation Criteria / Parameter
Supervisor	30	Problem formulation
	10	Literature review
	10	Proposed methodology
	10	Documentation
	50	Total
Departmental Committee (Chairperson BoS, Osmania University and Head, Supervisor & Project coordinator from the respective department of the institution)	15	Relevance of the Topic
	15	PPT Preparation
	10	Documentation
	10	Question and Answers
	50	Total

Guidelines for awarding marks in SEE (Semester End Examination): Max. Marks: 100		
Evaluation by	Max. Marks	Evaluation Criteria / Parameter
External Examiner and Chairperson, BoS & Head of the department (All together)	100	Proposed methodology, Literature review, Documentation, Power Point Presentation, Quality of thesis and evaluation Innovations, application to society and Scope for future study, Viva-Voce

***The student has to work a minimum of 32 hours/week at Dissertation – II.**